E9 205 Machine Learning for Signal Procesing

Support Vector Machines

12-10-2018







Linear Classifiers

- denotes +1
- denotes -1 0



X

How would you classify this data?

yest









Linear Classifiers

- denotes +1
- denotes -1 0



Define the margin of a linear classifier as the width that the boundary could be increased by before hitting a datapoint.

/est

Maximum Margin



Non-linear SVMs

 Datasets that are linearly separable with some noise work out great:



But what are we going to do if the dataset is just too hard?



How about... mapping data to a higher-dimensional space:



Non-linear SVMs: Feature spaces

 General idea: the original input space can always be mapped to some higher-dimensional feature space where the training set is separable:



The "Kernel Trick"

- The linear classifier relies on dot product between vectors $k(x_i, x_j) = x_i^T x_j$
- If every data point is mapped into high-dimensional space via some transformation $\Phi: \mathbf{x} \rightarrow \phi(\mathbf{x})$, the dot product becomes:

 $k(\mathbf{x}_i, \mathbf{x}_j) = \phi(\mathbf{x}_i)^{\mathrm{T}} \phi(\mathbf{x}_j)$

- A *kernel function* is some function that corresponds to an inner product in some expanded feature space.
- Example:

2-dimensional vectors $\mathbf{x} = [x_1 \ x_2]$; let $k(\mathbf{x}_i, \mathbf{x}_j) = (1 + \mathbf{x}_i^T \mathbf{x}_j)^2$

Need to show that $K(\mathbf{x}_{i}, \mathbf{x}_{j}) = \phi(\mathbf{x}_{i})^{T} \phi(\mathbf{x}_{j})$:

 $k(\mathbf{x}_{i},\mathbf{x}_{j}) = (1 + \mathbf{x}_{i}^{T}\mathbf{x}_{j})^{2}$

 $= 1 + x_{i1}^2 x_{j1}^2 + 2 x_{i1} x_{j1} x_{i2} x_{j2} + x_{i2}^2 x_{j2}^2 + 2 x_{i1} x_{j1} + 2 x_{i2} x_{j2}$

 $= \begin{bmatrix} 1 & x_{i1}^2 \sqrt{2} & x_{i1}x_{i2} & x_{i2}^2 \sqrt{2}x_{i1} \sqrt{2}x_{i2} \end{bmatrix}^{T} \begin{bmatrix} 1 & x_{j1}^2 \sqrt{2} & x_{j1}x_{j2} & x_{j2}^2 \sqrt{2}x_{j1} \sqrt{2}x_{j2} \end{bmatrix}$

= $\phi(\mathbf{x_i}) T \phi(\mathbf{x_j})$, where $\phi(\mathbf{x}) = \begin{bmatrix} 1 & x_1^2 \sqrt{2} & x_1 x_2 & x_2^2 & \sqrt{2} x_1 & \sqrt{2} x_2 \end{bmatrix}$

What Functions are Kernels?

For many functions k(x_i,x_i) checking that

 $\mathbf{K} =$

 $k(\mathbf{x}_{i}, \mathbf{x}_{j}) = \phi(\mathbf{x}_{i})^{T} \phi(\mathbf{x}_{j})$ can be cumbersome.

- Mercer's theorem: Every semi-positive definite symmetric function is a kernel
 - Semi-positive definite symmetric functions correspond to a semi-positive definite symmetric Gram matrix:

$k(\mathbf{x}_1,\mathbf{x}_1)$	$k(\mathbf{x_1},\mathbf{x_2})$	$k(\mathbf{x}_1,\mathbf{x}_3)$	•••	$k(\mathbf{x}_1, \mathbf{x}_N)$
$k(x_2, x_1)$	$k(\mathbf{x_2},\mathbf{x_2})$	$k(\mathbf{x}_2,\mathbf{x}_3)$		$k(\mathbf{x}_2, \mathbf{x}_N)$
•••	•••	•••	•••	•••
$k(\mathbf{x}_{N},\mathbf{x}_{1})$	$k(\mathbf{x}_{N},\mathbf{x}_{2})$	$k(\mathbf{X}_{N},\mathbf{X}_{3})$	•••	$k(\mathbf{x}_{N},\mathbf{x}_{N})$

Examples of Kernel Functions

- Linear: $k(\mathbf{x}_{i'}\mathbf{x}_{j}) = \mathbf{x}_{i}^{T}\mathbf{x}_{j}$
- Polynomial of power $p: k(\mathbf{x}_i, \mathbf{x}_j) = (1 + \mathbf{x}_i^T \mathbf{x}_j)^p$
- Gaussian (radial-basis function network):

$$k(\mathbf{x}_i, \mathbf{x}_j) = \exp \frac{-||\mathbf{x}_i - \mathbf{x}_j||^2}{\sigma^2}$$

• Sigmoid: $k(\mathbf{x}_{i}, \mathbf{x}_{j}) = \tanh(\beta_0 \mathbf{x}_i^T \mathbf{x}_j + \beta_1)$

SVM Formulation

> 2) Define the Margin $\frac{1}{||\mathbf{w}||} \min_n [t_n(\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_n) + b)]$

3) Maximize the Margin

$$argmax_{\mathbf{w},b} \left\{ \frac{1}{||\mathbf{w}||} min_n \left[t_n(\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_n) + b) \right] \right\}$$

Equivalently written as

 $\operatorname{argmin}_{\mathbf{w},b} \frac{1}{2} ||\mathbf{w}||^2$ such that $t_n(\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_n) + b) \ge 1$

Solving the Optimization Problem

- Need to optimize a *quadratic* function subject to *linear* constraints.
- Quadratic optimization problems are a well-known class of mathematical programming problems, and many (rather intricate) algorithms exist for solving them.
- The solution involves constructing a *dual problem* where a *Lagrange multiplier a_n* is associated with every constraint in the primary problem:
- The dual problem in this case is maximized

Find
$$\{a_1, ..., a_N\}$$
 such that
 $\tilde{L}(\mathbf{a}) = \sum_{n=1}^{N} a_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} t_n t_m a_n a_m k(\mathbf{x}_n, \mathbf{x}_m)$ maximized
and $\sum_n a_n t_n = 0$, $a_n \ge 0$

Solving the Optimization Problem

• The solution has the form:

 $\mathbf{w} = \sum_{n=1}^{\infty} a_n \boldsymbol{\phi}(\mathbf{x}_n)$

Each non-zero a_n indicates that corresponding x_n is a support vector. Let S denote the set of support vectors.

$$b = y(\mathbf{x}_n) - \sum_{m \in S} a_m k(\mathbf{x}_m, \mathbf{x}_n)$$

And the classifying function will have the form:

$$y(\mathbf{x}) = \sum_{n \in S} a_n k(\mathbf{x}_n, \mathbf{x}) + b$$

Solving the Optimization Problem



Visualizing Gaussian Kernel SVM



Overlapping class boundaries

- The classes are not linearly separable Introducing slack variables ζ_n
- Slack variables are non-negative $\zeta_n \ge 0$
- They are defined using

 $t_n y(\mathbf{x}_n) \ge 1 - \zeta_n$

• The upper bound on mis-classification $\sum_{n} \zeta_{n}$



The cost function to be optimized in this case

$$C\sum_{n}\zeta_{n}+rac{1}{2}\mathbf{w}^{T}\mathbf{w}$$

SVM Formulation - overlapping classes

 Formulation very similar to previous case except for additional constraints

 $0 \le a_n \le C$

- Solved using the dual formulation sequential minimal optimization algorithm
- Final classifier is based on the sign of

$$y(\mathbf{x}) = \sum_{n \in S} a_n k(\mathbf{x}_n, \mathbf{x}) + b$$

Overlapping class boundaries

