#### E9 205 Machine Learning for Signal Processing

ML, MAP, MMSE and Gaussian Modeling

12-09-2016





### Recap ...

- Decision Theory
  - \* Inference problem
    - \* Finding the joint density  $p(\mathbf{x}, \mathbf{t})$
  - \* Decision problem
    - \* Using the inference to make the classification or regression decision

### Decision Problem - Classification

- Minimizing the mis-classification error
- Decision based on maximum posteriors

$$argmax_j \ p(C_j|\mathbf{x})$$

- Loss matrix
  - Minimizing the expected loss

$$argmax_j \sum_k L_{k,j} p(C_k|\mathbf{x})$$

### Approaches for Inference and Decision

I. Finding the joint density from the data.

$$p(C_k|\mathbf{x}) \propto p(\mathbf{x}|C_k)p(C_k)$$

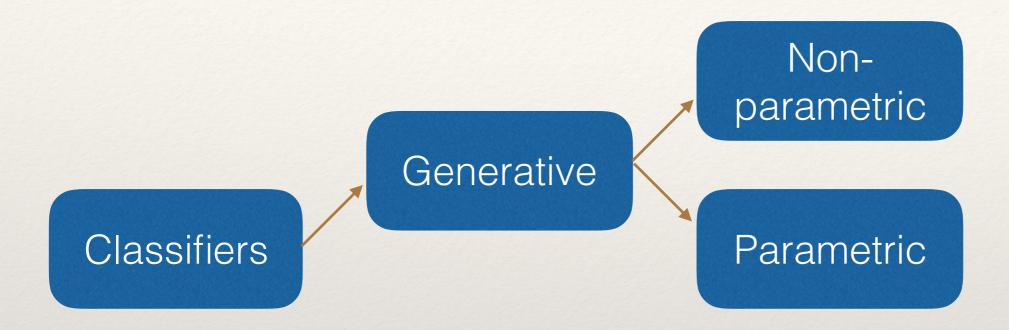
II. Finding the posteriors directly.

III. Using discriminant functions for classification.

# Decision Rule for Regression

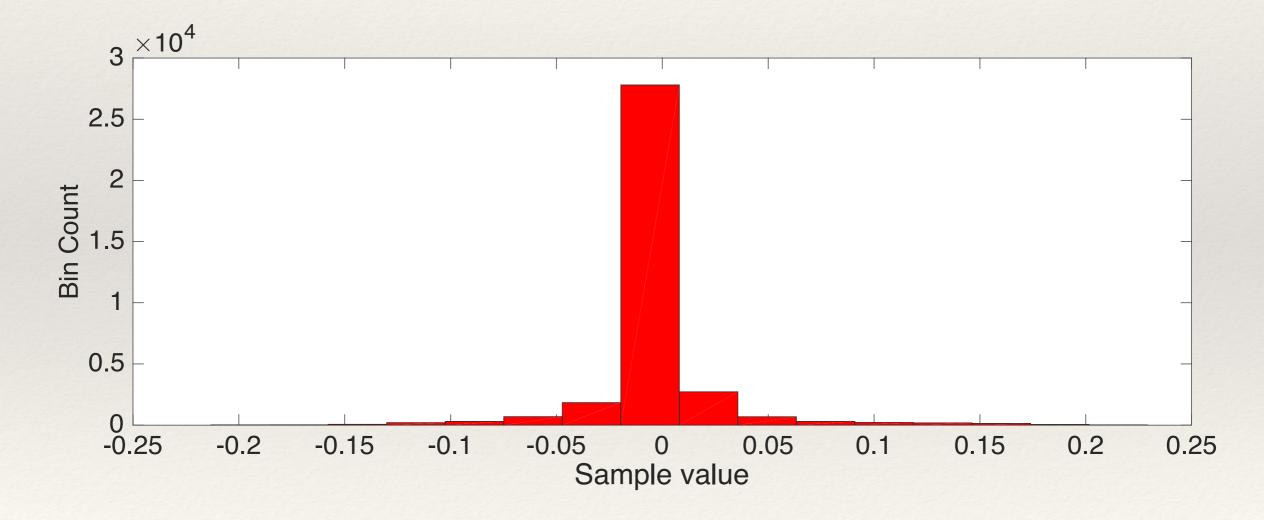
- \* Minimum mean square error loss
- \* Solution is conditional expectation.

## Generative Modeling



# Non-parametric Modeling

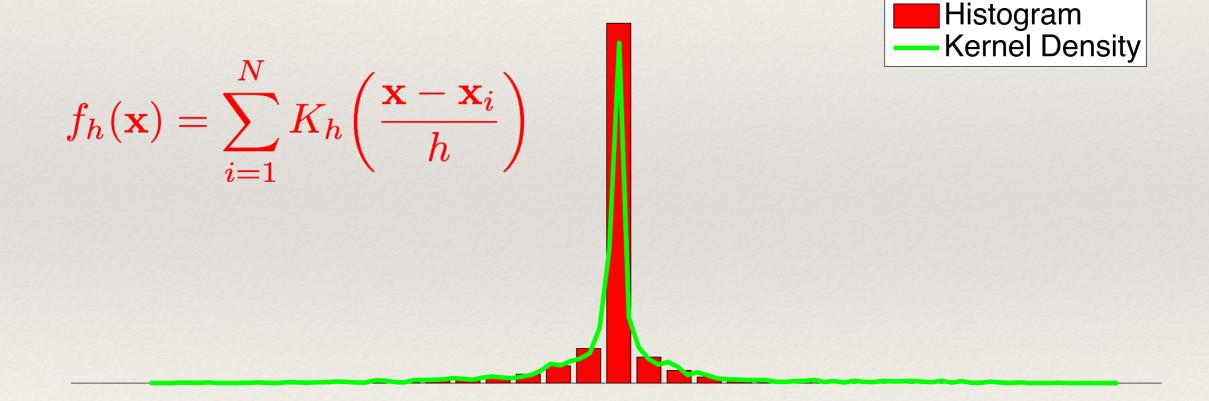
• Non-parametric models do not specify an apriori set of parameters to model the distribution. Example - Histogram



The density is not smooth and has block like shape.

# Non-parametric Modeling

- Non-parametric models do not specify an apriori set of parameters to model the distribution.
  - Example Kernel Density Estimators



Kernel is a smooth function which obeys certain properties

# Non-parametric Modeling

- Non-parametric methods are dependent on number of data points
  - Estimation is difficult for large datasets.
- Likelihood computation and model comparisons are hard.
- Limited use in classifiers

### Parametric Models

\* Collection of probability distributions which are described by a finite dimensional parameter set

$$\boldsymbol{\theta} = (\theta_1, \theta_2, ... \theta_K) \qquad P = \{P_{\boldsymbol{\theta}}\}$$

- Examples -
  - Poisson Distribution

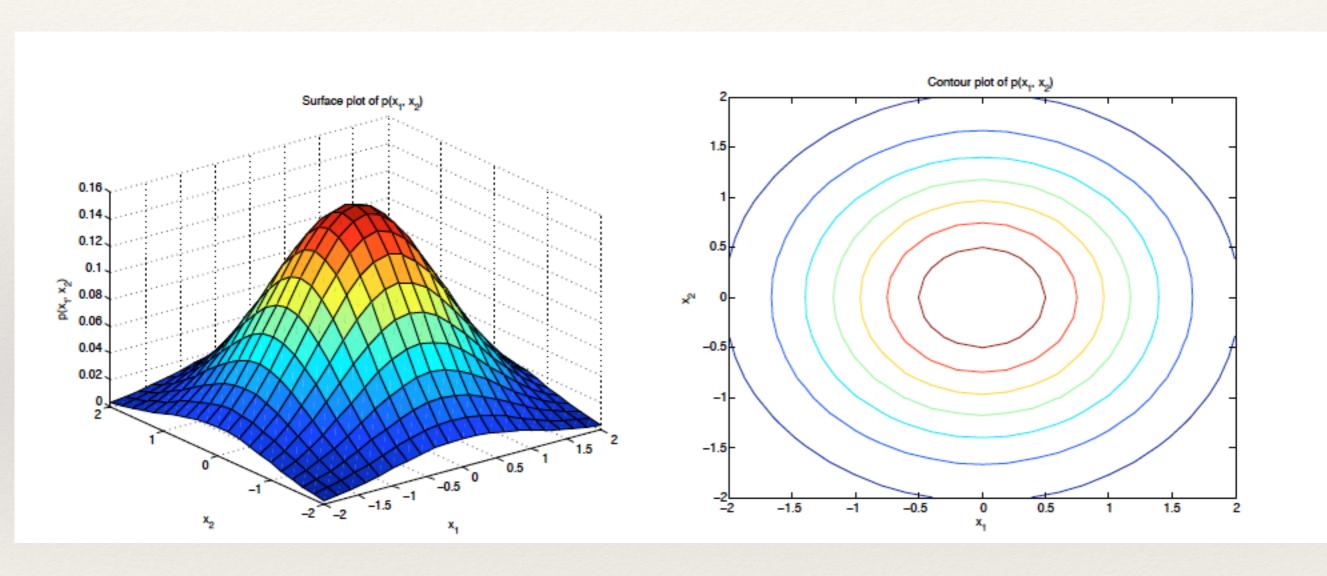
$$p_{\lambda}(j) = \frac{\lambda^{j}}{j!} e^{-\lambda}$$

Bernoulli Distribution

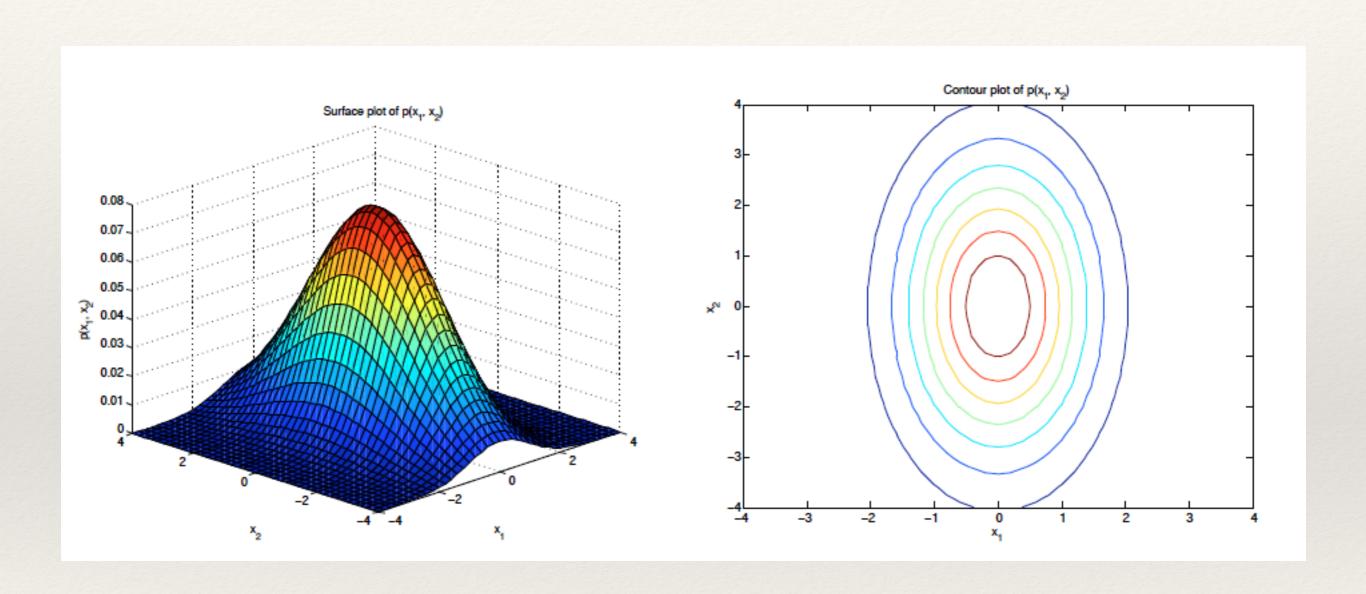
$$p(\mathbf{x}|\boldsymbol{\mu}) = \prod_{i=1}^{D} \mu_i^{x_i} (1 - \mu_i)^{x_i}$$

Gaussian Distribution

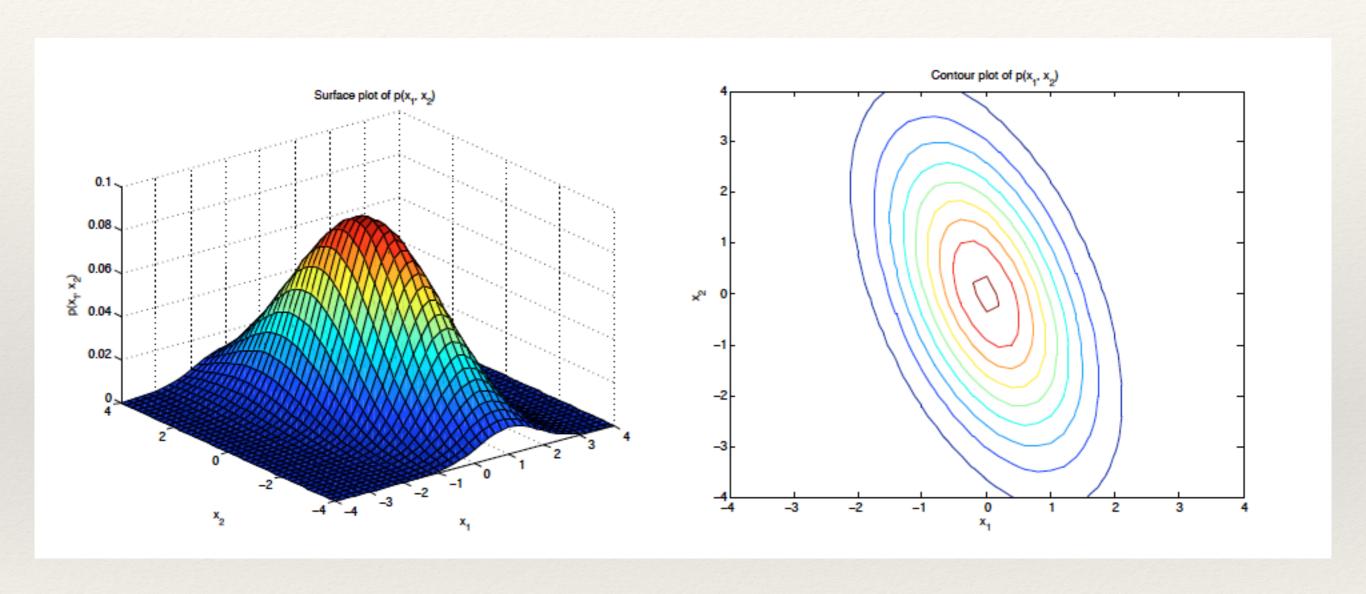
$$p(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^* \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\}$$



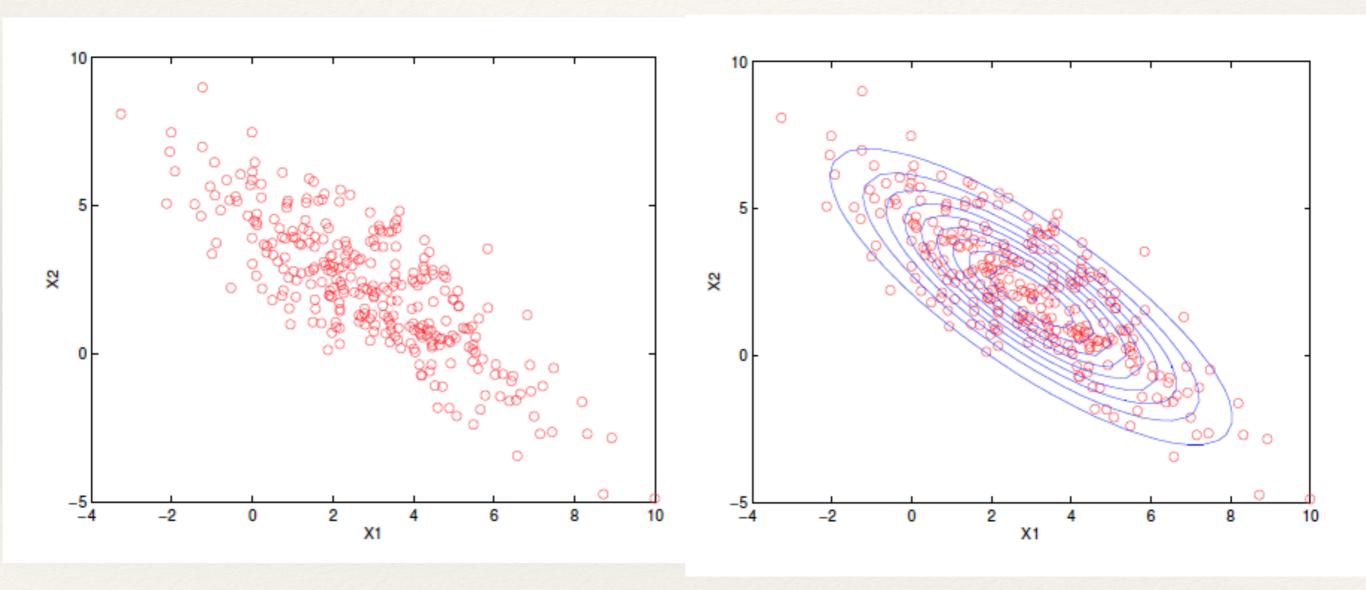
Points of equal probability lie on on contour Diagonal Gaussian with Identical Variance



Diagonal Gaussian with different variance



Full covariance Gaussian distribution



### Finding the parameters of the Model

The Gaussian model has the following parameters

$$\boldsymbol{\theta} = (\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

- \* Total number of parameters to be learned for D dimensional data is  $D^2 + D$
- \* Given N data points  $\{x_i\}_{i=1}^N$  how do we estimate the parameters of model.
  - Several criteria can be used
  - The most popular method is the maximum likelihood estimation (MLE).

#### MLE

Define the likelihood function as  $L(\theta) = \prod_{i=1}^{p} p(\mathbf{x}_i | \theta)$ 

The maximum likelihood estimator (MLE) is

$$\boldsymbol{\theta}^* = arg \max_{\boldsymbol{\theta}} L(\boldsymbol{\theta})$$

The MLE satisfies nice properties like

- Consistency (covergence to true value)
- Efficiency (has the least Mean squared error).





#### MLE

#### For the Gaussian distribution

$$p(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^* \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\}$$

$$L(\boldsymbol{\theta}) = \prod_{i=1}^{N} p(\mathbf{x}_i | \boldsymbol{\theta})$$

$$\log L(\boldsymbol{\theta}) = -\frac{ND}{2} - \frac{N}{2} \log |\boldsymbol{\Sigma}| - \frac{1}{2} \sum_{i=1}^{N} \left( (\mathbf{x}_i - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) \right)$$

To estimate the parameters  $\frac{\partial \log L}{\partial u} = 0$ 

$$\frac{\partial \log L}{\partial \boldsymbol{\mu}} = 0$$



