E9 205 Machine Learning for Signal Processing

Mixture Gaussian Modeling and EM Algorithm

14-09-2016





Gaussian Distribution Summary

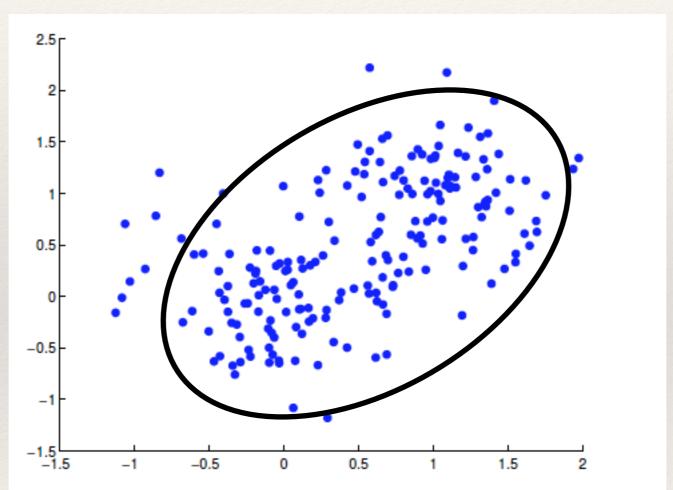
- The Gaussian model parametric distributions
- * Simple and useful properties.
- Can model unimodal (single peak distributions)
- MLE gives intuitive results
- Issues with Gaussian model
 - Multi-modal data
 - Not useful for complex data distributions
- * Need for mixture models





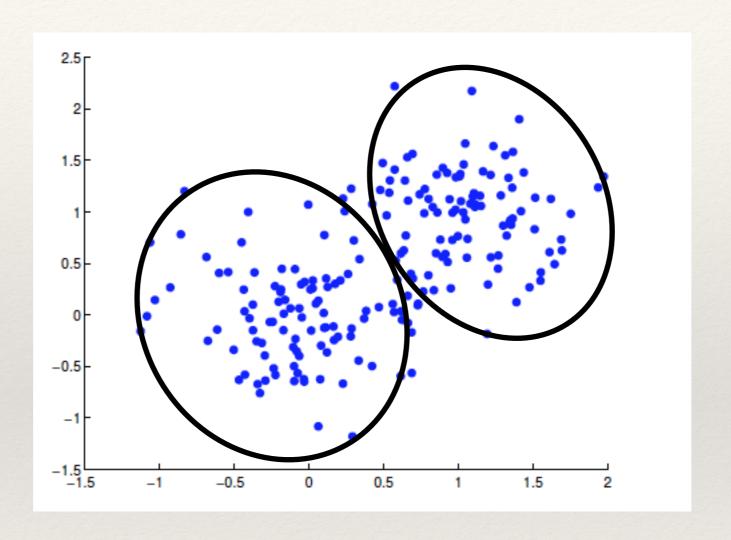
Gaussian Distribution

Often the data lies in clusters (2-D example)



Fitting a single Gaussian model may be too broad.

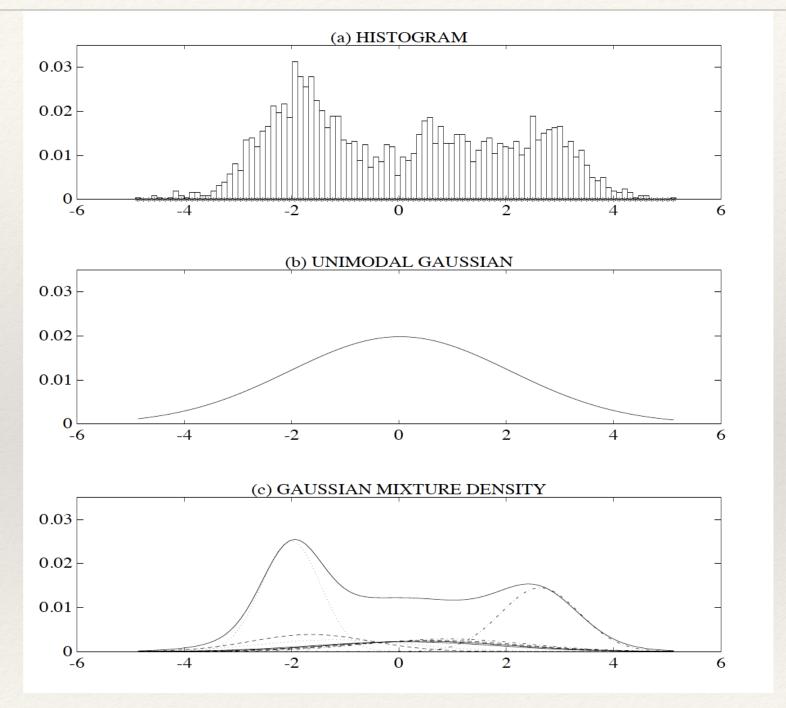
Gaussian Distribution



Need mixture models

Can fit any arbitrary distribution.

Gaussian Distribution



1-D example

Often the data lies in clusters

Gaussian Mixture Models

A Gaussian Mixture Model (GMM) is defined as

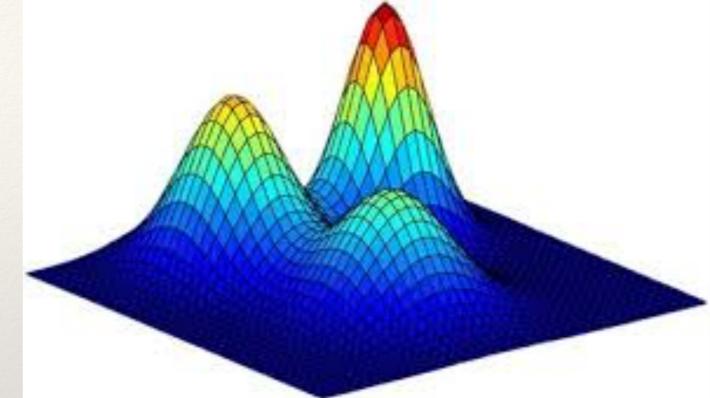
$$p(\mathbf{x}|\mathbf{\Theta}) = \sum_{k=1}^{K} \alpha_k p(\mathbf{x}|\mathbf{\theta}_k)$$
$$p(\mathbf{x}|\mathbf{\theta}_k) = \frac{1}{\sqrt{(2\pi)^D |\mathbf{\Sigma}_k|}} exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^* \mathbf{\Sigma}_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k) \right\}$$

The weighting coefficients have the property

$$\sum_{k=1}^{K} \alpha_k = 1$$

Gaussian Mixture Models

- Properties of GMM
 - Can model multi-modal data.
 - Identify data clusters.
 - Can model arbitrarily complex data distributions



The set of parameters for the model are

$$\mathbf{\Theta}_k = \{\alpha_k, \boldsymbol{\theta}_k\}_{k=1}^K \quad \boldsymbol{\theta}_k = \{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k\}$$

The number of parameters is $KD^2 + KD + K$

MLE for GMM

* The log-likelihood function over the entire data in this case will have a logarithm of a summation

$$\log L(\mathbf{\Theta}) = \sum_{i=1}^{N} \log \left(\sum_{k=1}^{K} \alpha_k p(\mathbf{x}_i | \boldsymbol{\theta}_k) \right)$$

- * Solving for the optimal parameters using MLE for GMM is not straight forward.
- * Resort to the Expectation Maximization (EM) algorithm

Expectation Maximization Algorithm

- * Iterative procedure.
- * Assume the existence of hidden variable associated with each data sample
- * Let the current estimate (at iteration n) be Define the Q function as

$$Q(\mathbf{\Theta}, \mathbf{\Theta}^n) = E_{\mathbf{z}|\mathbf{X}, \mathbf{\Theta}^n} \left[\log(P(\mathbf{X}, \mathbf{z}|\mathbf{\Theta})) \right]$$
$$= \sum \log(P(\mathbf{X}, \mathbf{z}|\mathbf{\Theta})) P(\mathbf{z}|\mathbf{X}, \mathbf{\Theta}^n)$$

Expectation Maximization Algorithm

* It can be proven that if we choose

$$oldsymbol{\Theta}^{n+1} = arg\max_{oldsymbol{\Theta}} Q(oldsymbol{\Theta},oldsymbol{\Theta}^n)$$
 then $L(oldsymbol{\Theta}^{n+1}) \geq L(oldsymbol{\Theta}^n)$

- In many cases, finding the maximum for the Q function may be easier than likelihood function w.r.t. the parameters.
- Solution is dependent on finding a good choice of the hidden variables which eases the computation
- Iteratively improve the log-likelihood function.

EM Algorithm Summary

- Initialize with a set of model parameters (n=1)
- Compute the conditional expectation (E-step)

$$E_{\mathbf{z}|\mathbf{X},\mathbf{\Theta}^n} \left[\log(P(\mathbf{X},\mathbf{z}|\mathbf{\Theta})) \right]$$

- Maximize the conditional expectation w.r.t.
 parameter. (M-step) (n = n+1)
- Check for convergence
- Go back to E-step if model has not converged.

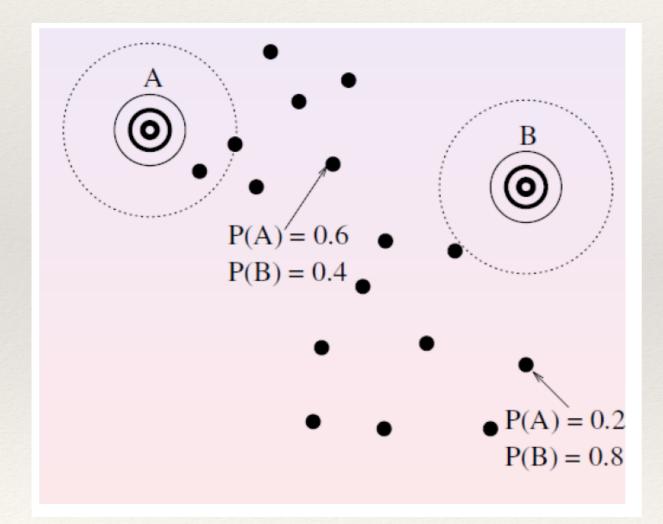
- * The hidden variables $\mathbf{z}_i = l$ will be the index of the mixture component which generated \mathbf{x}_i
- Re-estimation formulae

$$lpha_{\ell}^{new} = rac{1}{N} \sum_{i=1}^{N} p(\ell|x_i, \Theta^g)$$

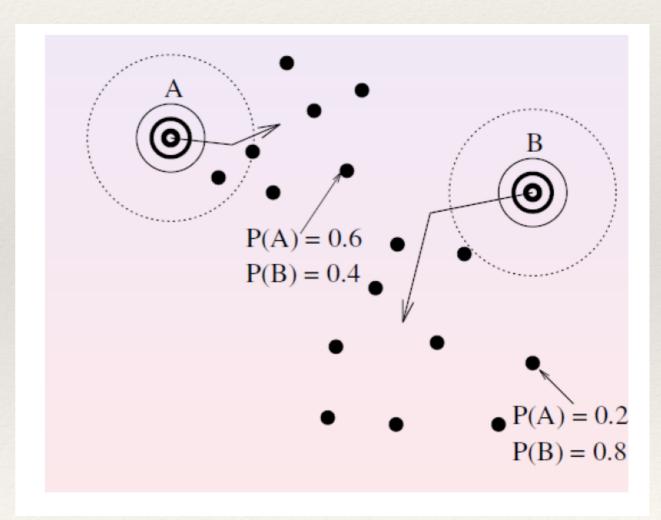
$$\mu_{\ell}^{new} = \frac{\sum_{i=1}^{N} x_i p(\ell|x_i, \Theta^g)}{\sum_{i=1}^{N} p(\ell|x_i, \Theta^g)}$$

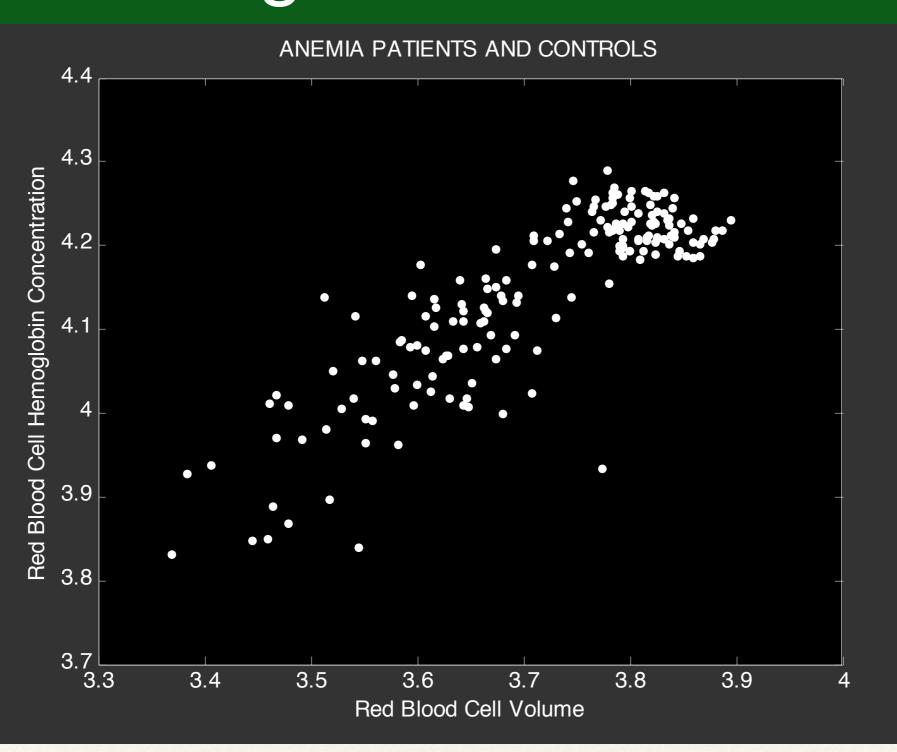
$$\Sigma_{\ell}^{new} = \frac{\sum_{i=1}^{N} p(\ell|x_i, \Theta^g)(x_i - \mu_{\ell}^{new})(x_i - \mu_{\ell}^{new})^T}{\sum_{i=1}^{N} p(\ell|x_i, \Theta^g)}$$

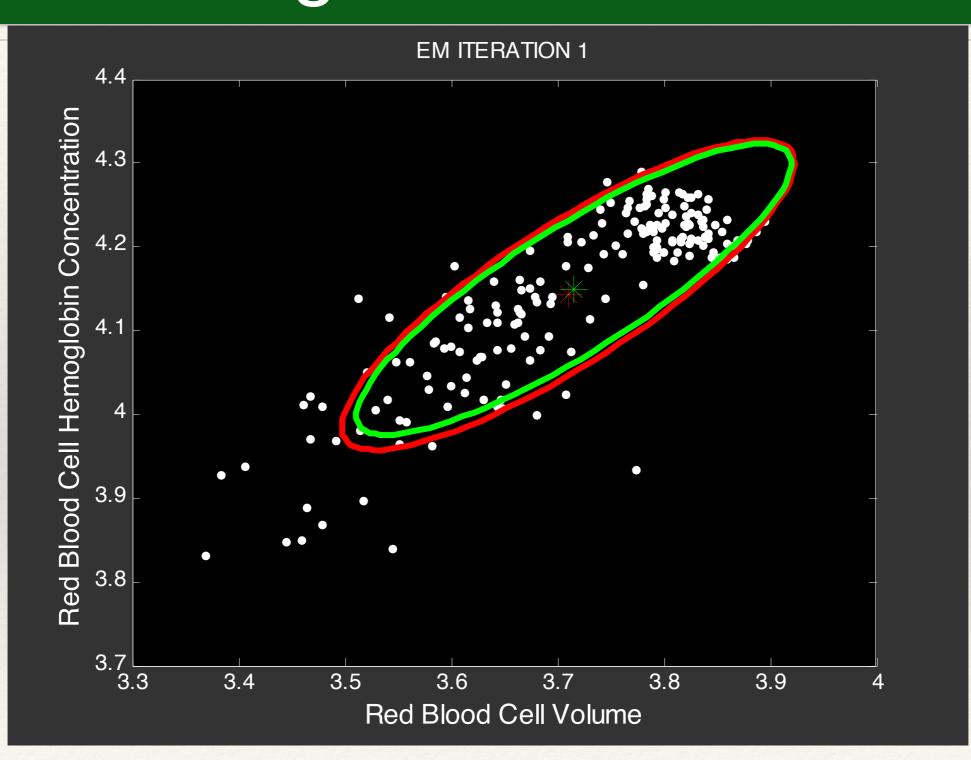
E-step

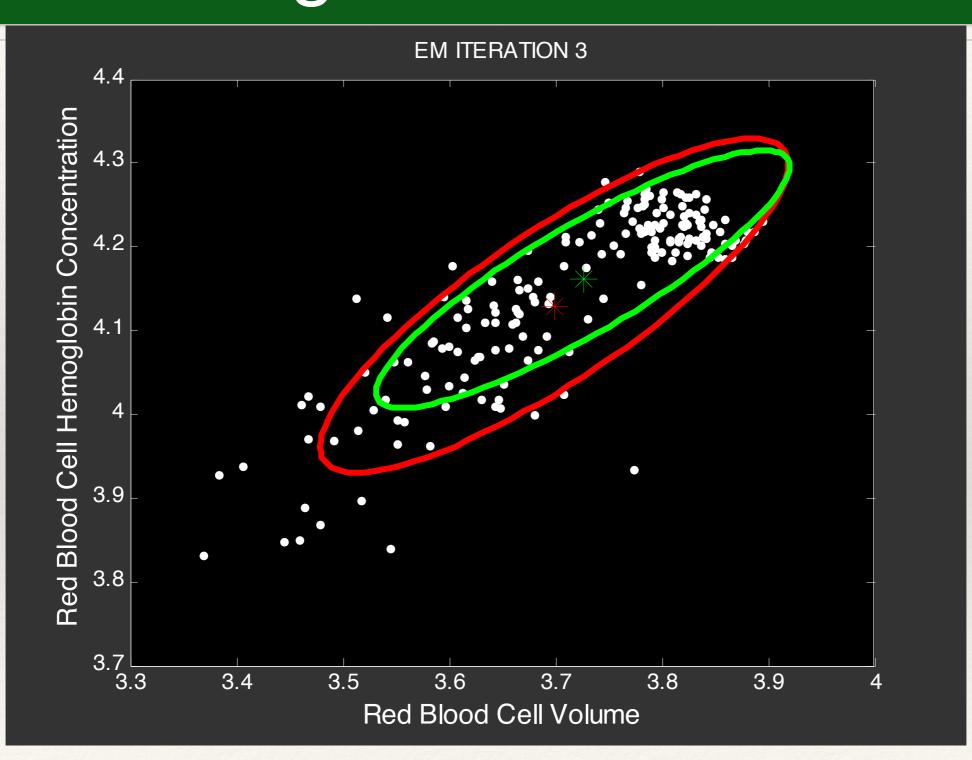


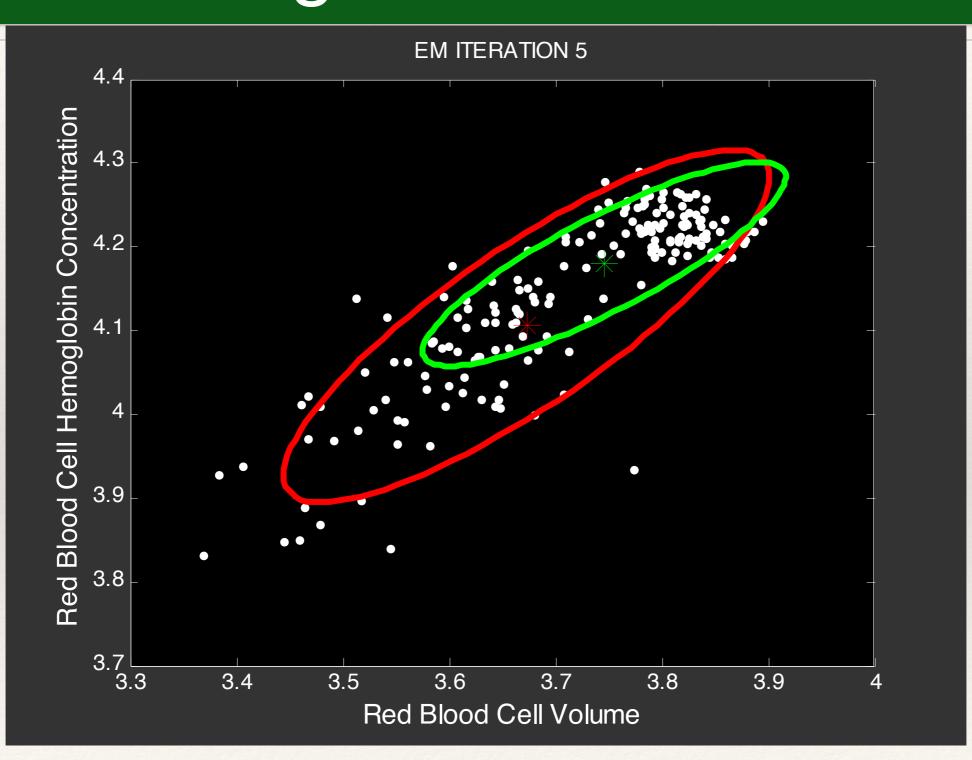
M-step

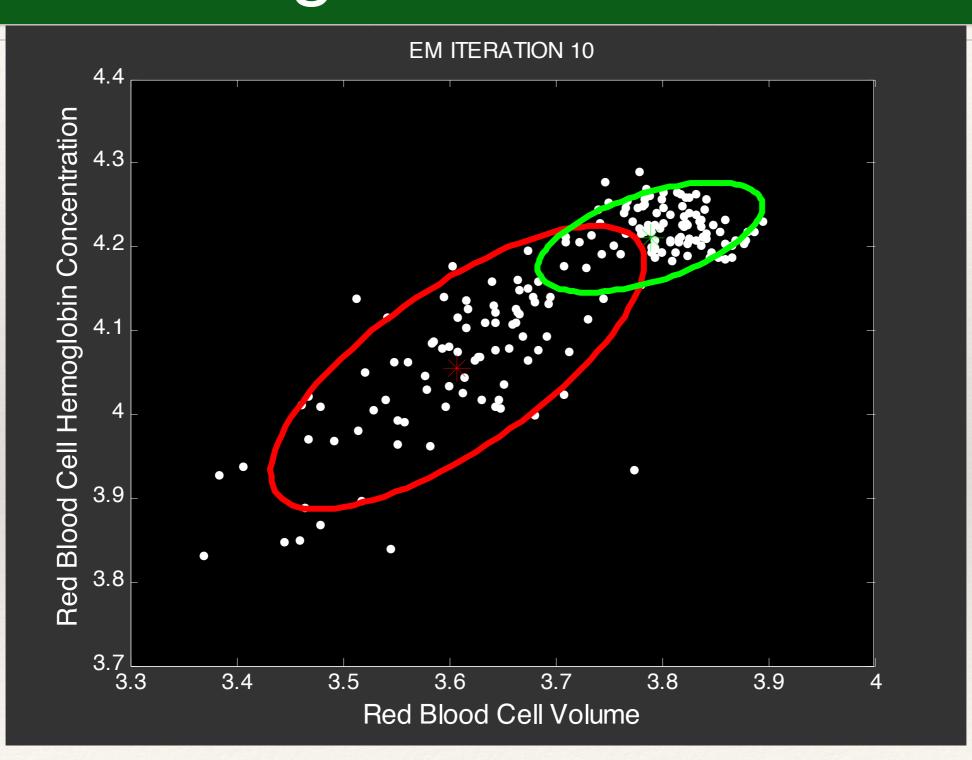


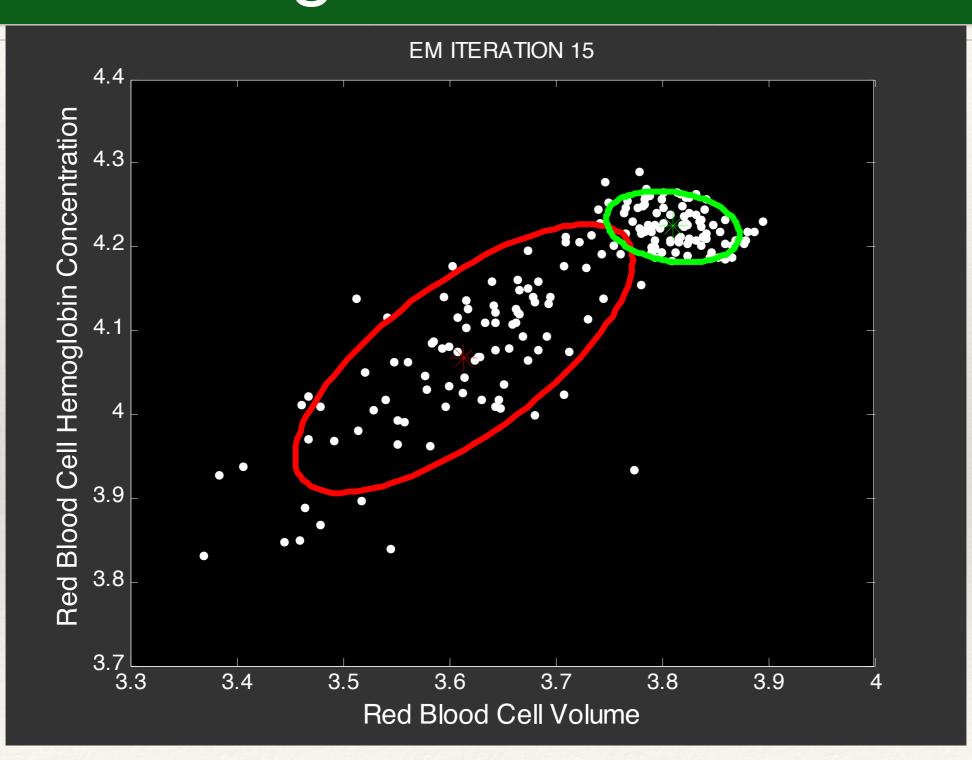


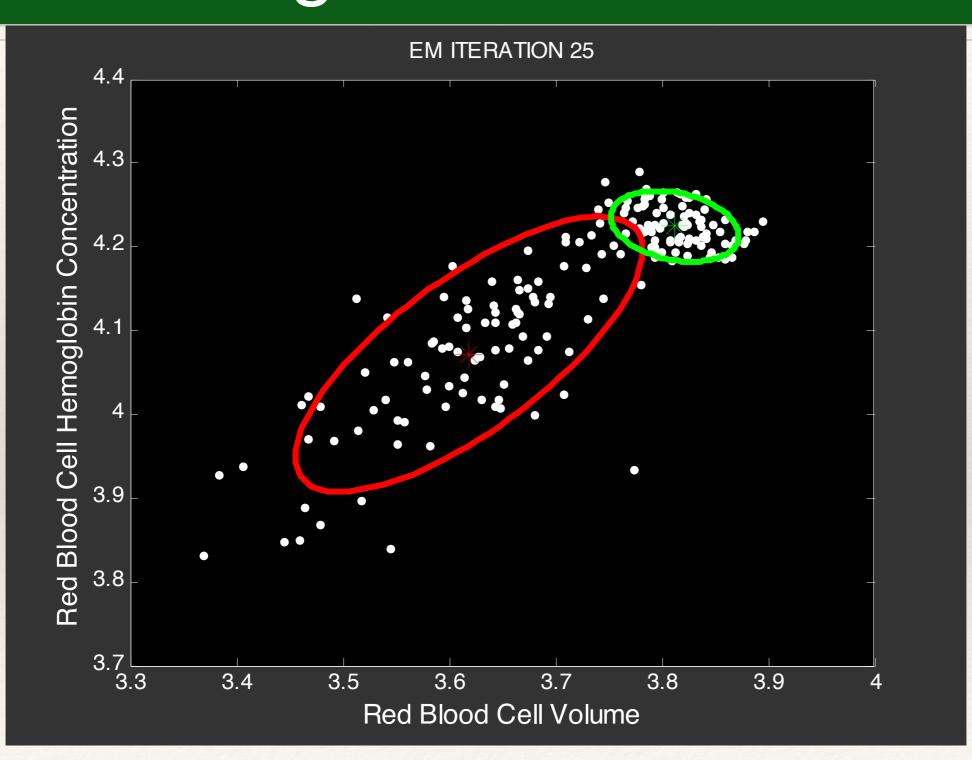


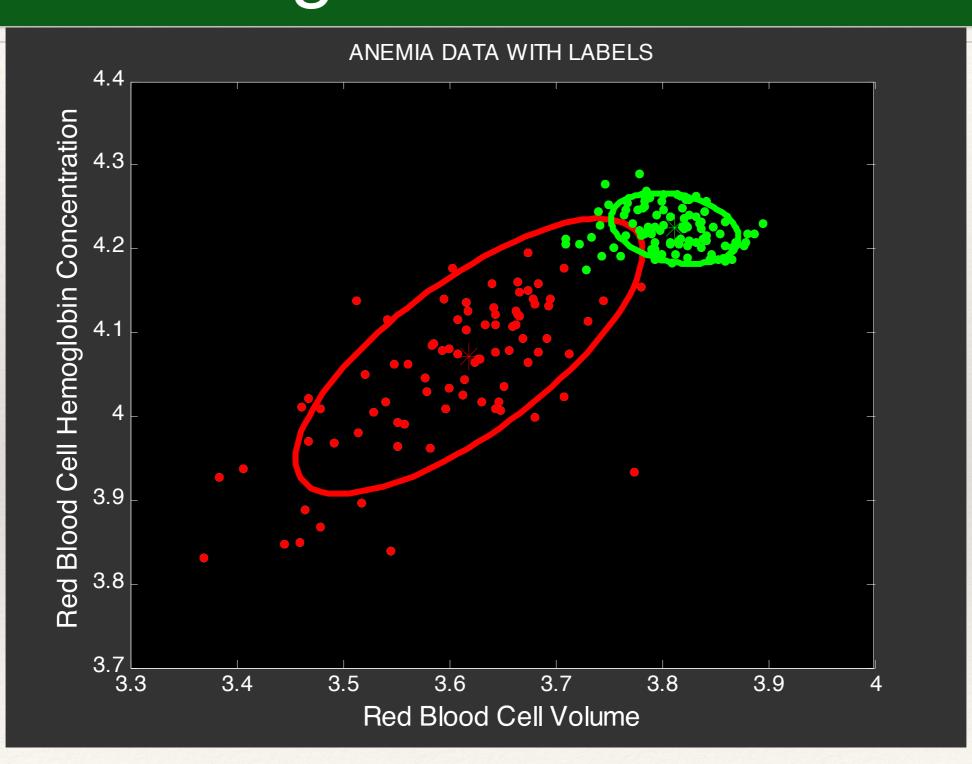




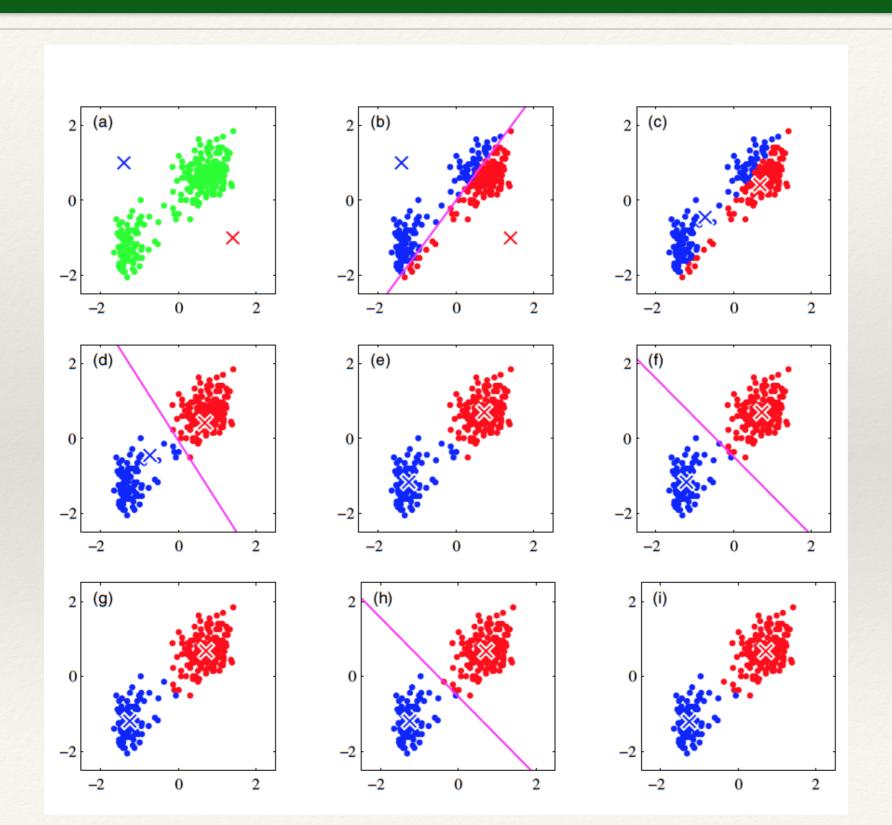






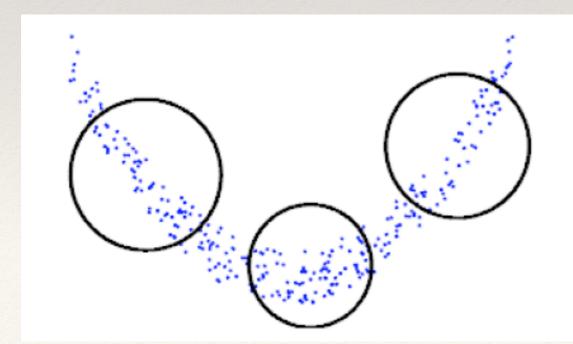


K-means Algorithm for Initialization



Other Considerations

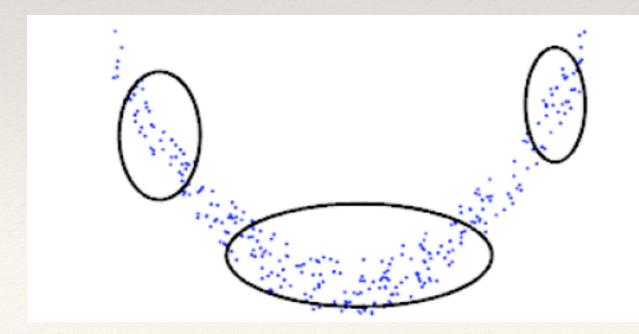
- Initialization random or k-means
- Number of Gaussians
- Type of Covariance matrix
 - Spherical covariance



- -Less precise.
- -Very efficient to compute.

Other Considerations

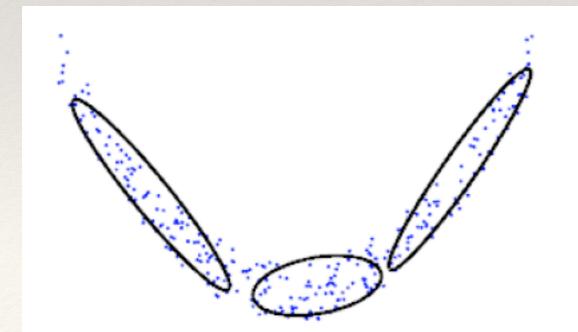
- Initialization random or k-means
- Number of Gaussians
- Type of Covariance matrix
 - Diagonal covariance



- -More precise.
- -Efficient to compute.

Other Considerations

- Initialization random or k-means
- Number of Gaussians
- Type of Covariance matrix
 - Full covariance



- -Very precise.
- -Less efficient to compute.