

E9: 309 ADL 16-12-2020

<http://leap.ee.iisc.ac.in/sriram/teaching/ADL2020/>

Recap from previous lectures

★ Analyzing trained neural networks

- ✓ Hierarchical representations ✓
- Maximizing activations ✓
- Visualizing representations ✓
- Reconstruction of input patterns from hidden layers. ✓

* Transferability of representations



Today's lecture

★ Why models predict what they predict



Architecture updates for interpretability

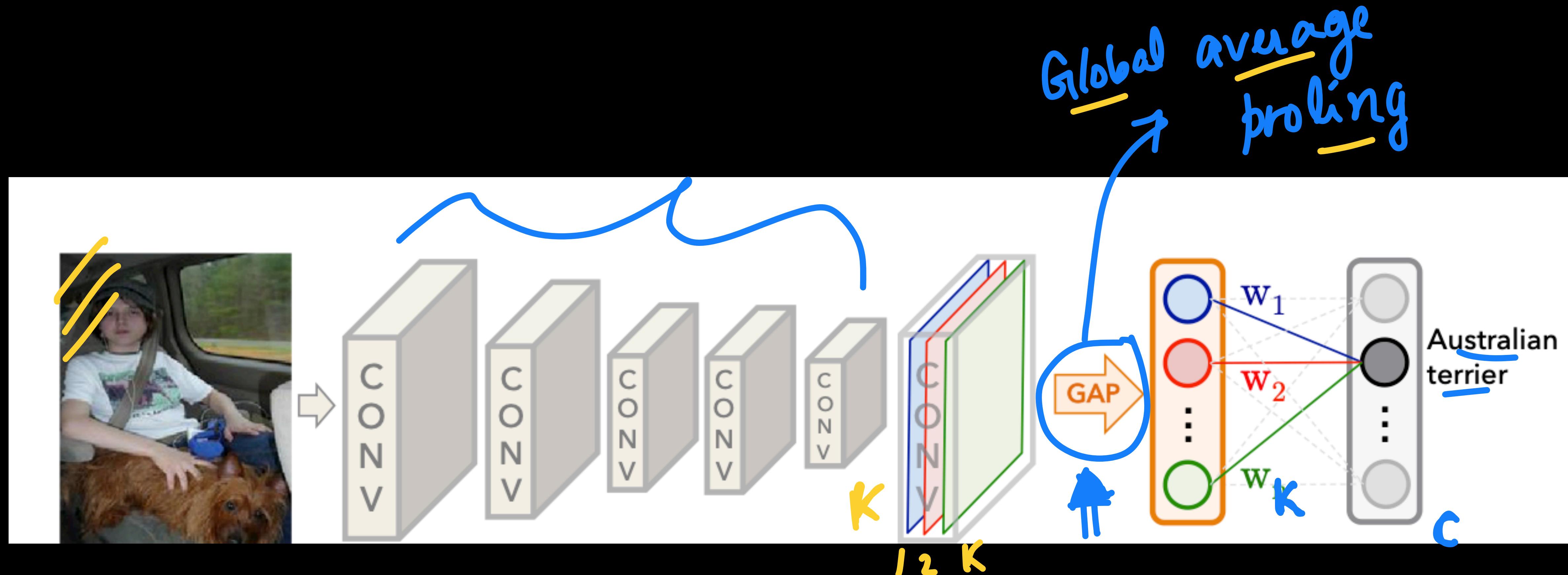
Learning Deep Features for Discriminative Localization

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2015



Learning the input pattern of a trained network



Architecture updates for interpretability

★ Global average pooling

$$F^{k,L} = \sum_{i,j} \mathbf{f}^{k,L}(i,j)$$

k - index of feature

map

k = 1..K

L - last layer

★ Last layer mapping to classes

$$a^{c,L} = \sum_{k=1}^K w_c^{k,L} F^{k,L}$$

$$\hat{\mathbf{y}} = softmax(\mathbf{a}^L)$$

$$\underline{\mathbf{a}}^L$$

$$\begin{bmatrix} a^{1,L} \\ a^{2,L} \\ \vdots \\ a^{C,L} \end{bmatrix}$$



Architecture updates for interpretability

* Rearranging the terms

$$\begin{aligned} 1 \quad a^{c,L} &= \sum_{k=1}^K w_c^{k,L} \sum_{i,j} \mathbf{f}^{k,L}(i,j) \\ &= \sum_{i,j} \sum_{k=1}^K w_c^{k,L} \mathbf{f}^{k,L}(i,j) \end{aligned}$$

GAP

$a^{c,L} \xrightarrow{\text{activation}} \text{Output}$

Image

class activation
maps

* Defining the map

$$m^c(i,j) = \sum_{k=1}^K w_c^{k,L} \mathbf{f}^{k,L}(i,j)$$

class activation
maps



Architecture updates for interpretability

CAM

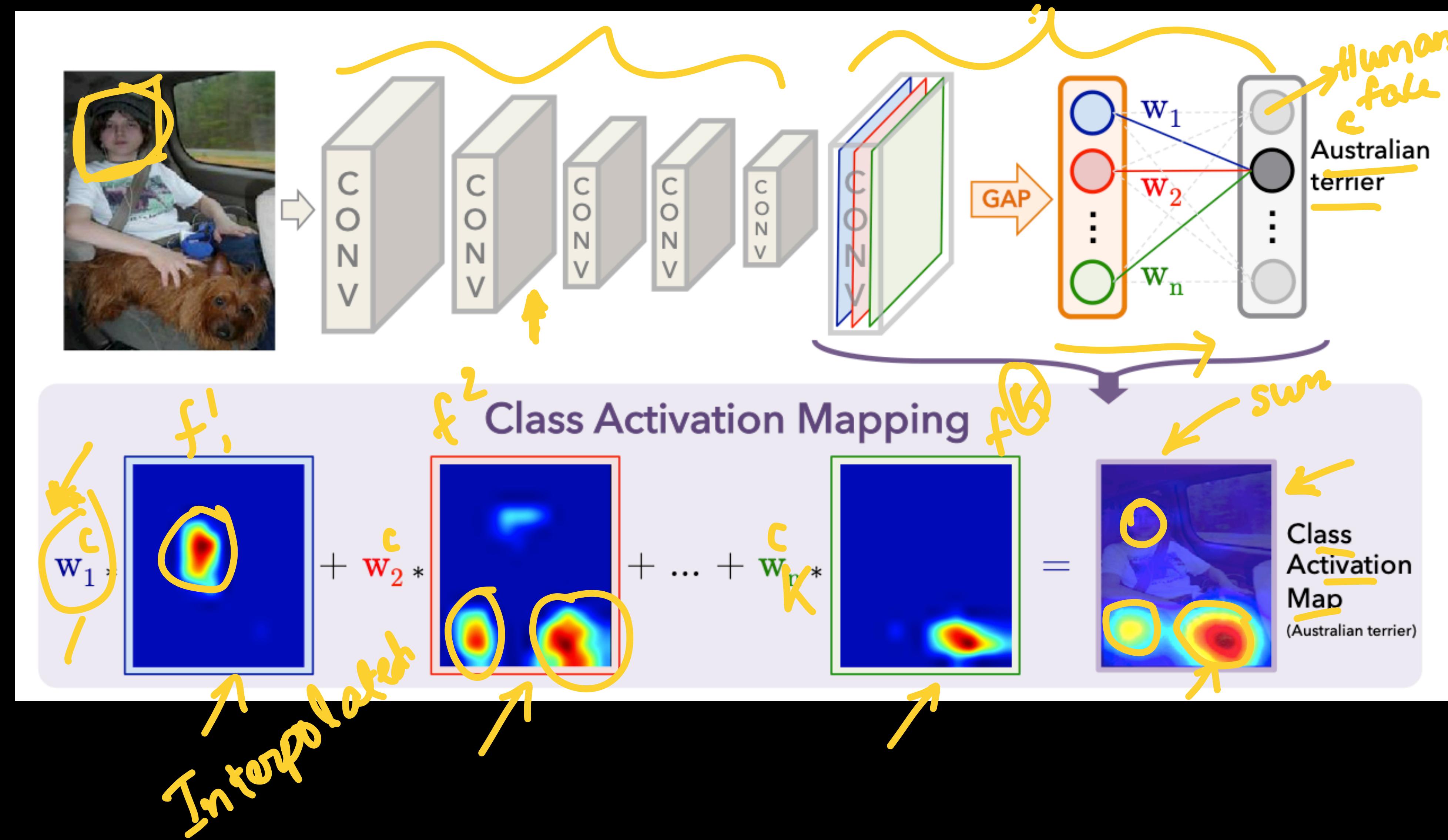
- ★ The maps denote spatial patterns that define how important a particular pixel is for that particular class.



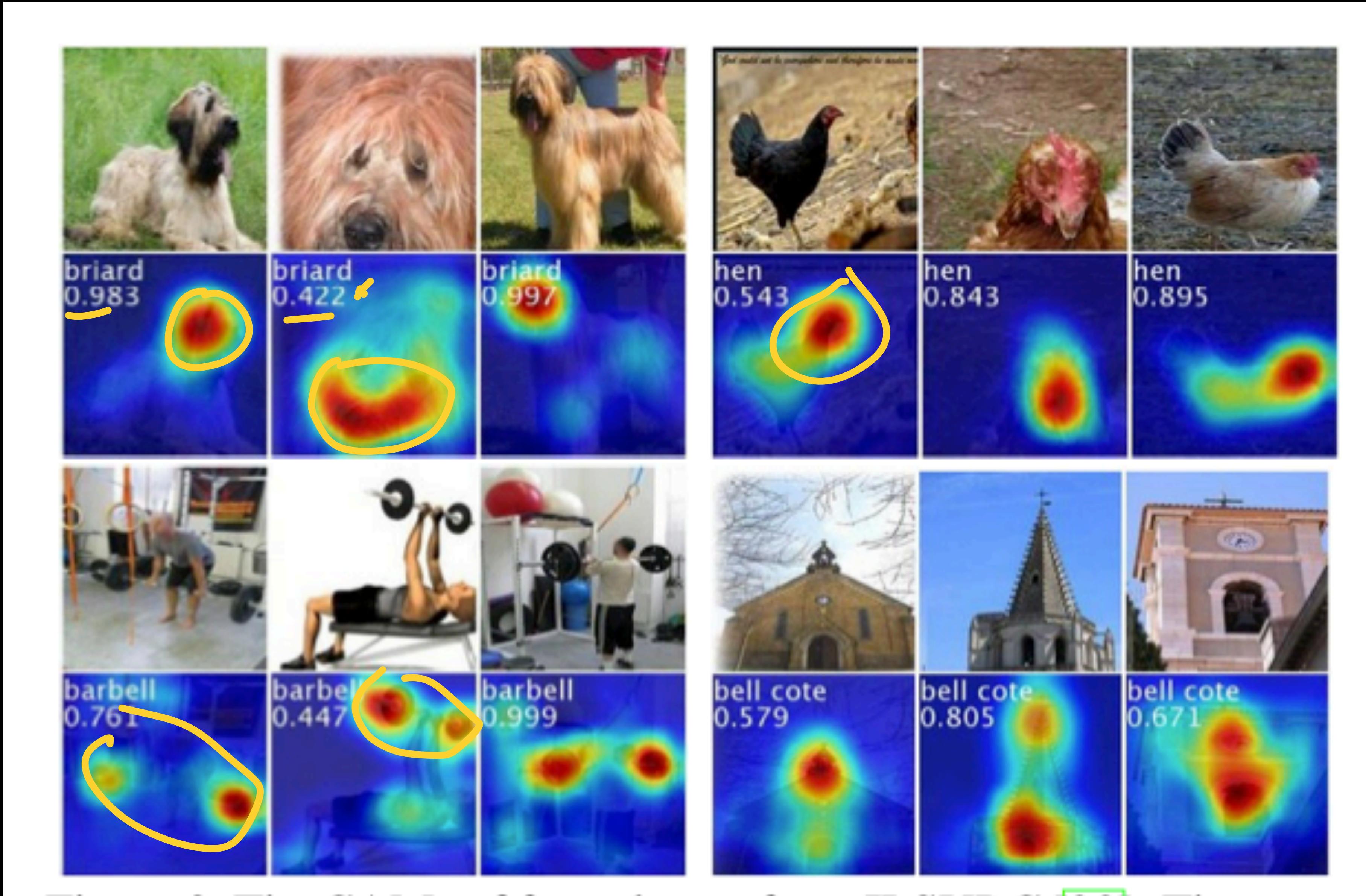
- ★ The map can be interpolated to the original input dimensions to visualize the pattern



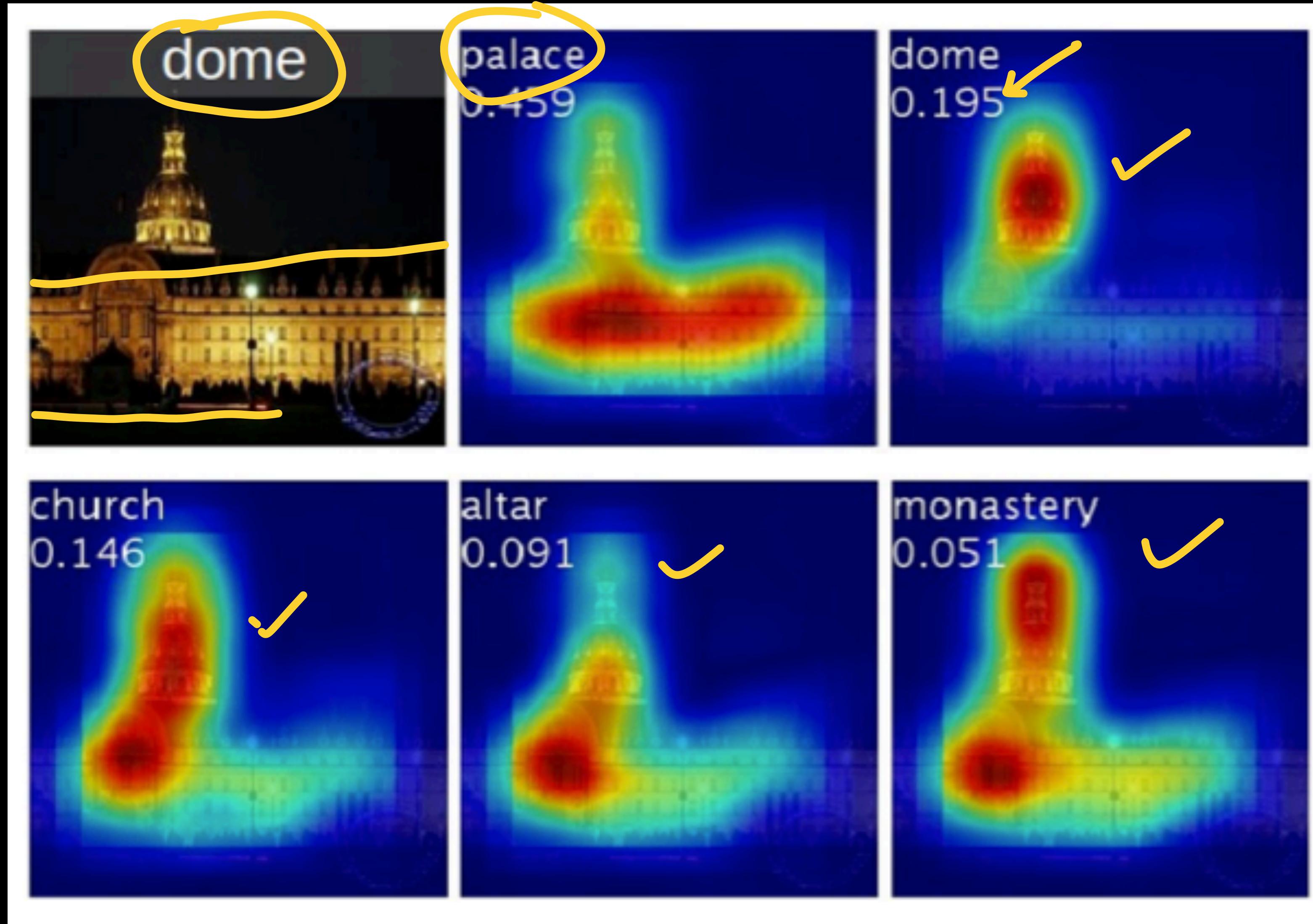
Architecture updates for interpretability



Architecture updates for interpretability



Architecture updates for interpretability



Architecture updates for interpretability

* Flaws in the approach

→ Requires Global average pooling based

→ The model may be inferior to the other models with fully connected layers after the CNN layers

Table 1. Classification error on the ILSVRC validation set.

Networks	top-1 val. error	top-5 val. error
VGGnet-GAP	33.4	12.2
GoogLeNet-GAP	35.0	13.2
AlexNet*-GAP	44.9	20.9
AlexNet-GAP	51.1 +	26.3 +
GoogLeNet	31.9	11.3
VGGnet	31.2	11.4
AlexNet	42.6	19.5



Grad-CAM : Visual Explanations . . .

Selvaraju et .al (2016
CVPR)

Improving CAM without compromising architecture

- * Find the gradient of the output activation with respect to the feature maps of the last convolutional layer

$$\alpha_k^c = \frac{1}{S} \sum_{i,j} \frac{\partial a^{c,L}}{\partial f^{k,l}(i,j)}$$

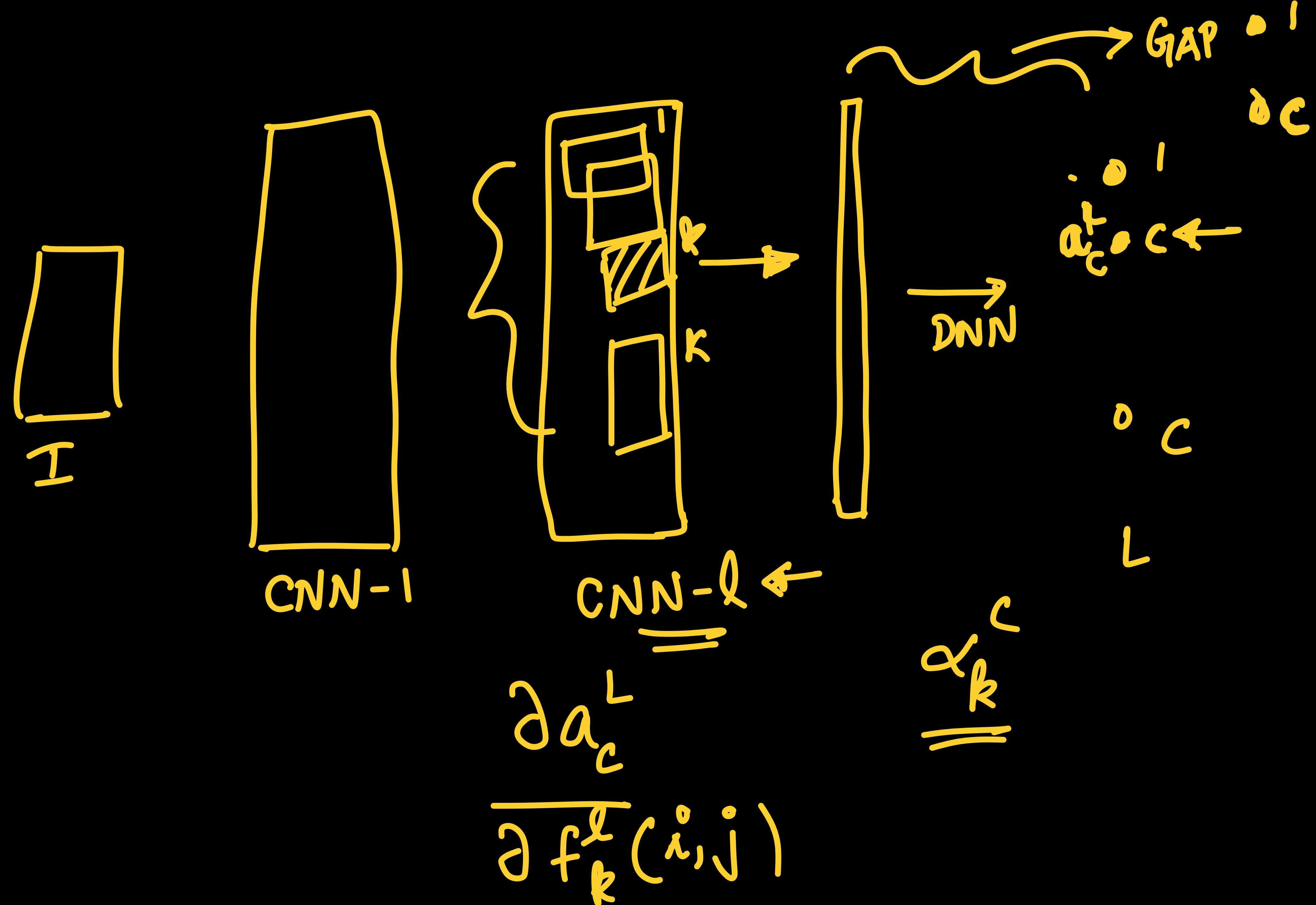
$$f^{k,l}(i,j)$$

- * Assumption - The feature maps from the last convolutional layer capture the spatial information as well as the semantic information required for classification.

$$S = \sum_{i,j} 1$$

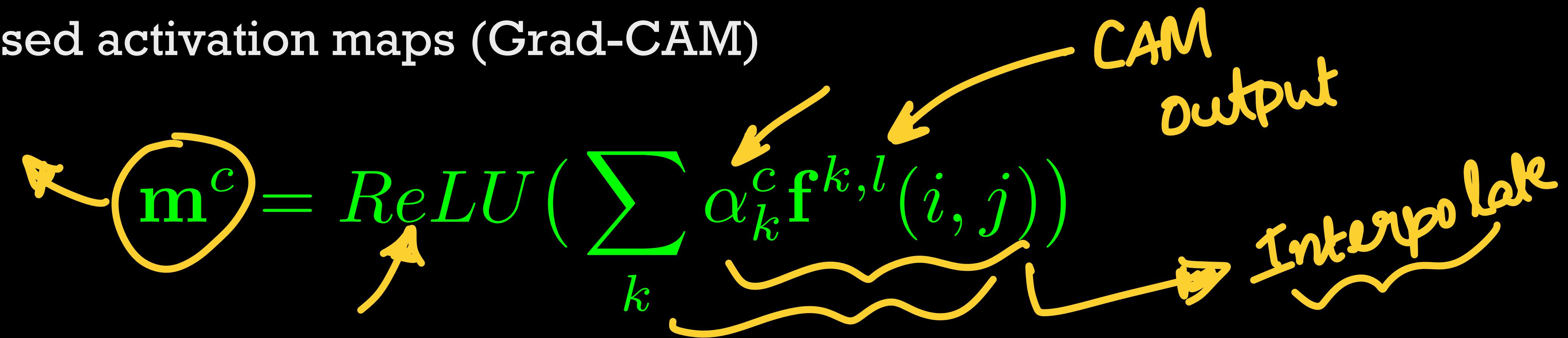
l - last CNN layer
k - feature map index





Improving CAM without compromising architecture

- ★ Gradient based activation maps (Grad-CAM)



- ★ Multiply the gradient based contribution to the individual pixels of the feature maps

- ★ The ReLU operation preserves only the pixels that have a positive influence on the output activations.

- ➡ The negative pixels may belong some other class category



Relation between CAM and Grad-CAM

- * If the last convolutional layer is followed by a global average pooling (GAP) and softmax layer then, Grad-CAM gives

$$F^{k,L} = \sum_{i,j} \mathbf{f}^{k,L}(i,j) \quad \overset{\text{GAP}}{=} \quad$$

- * The derivative output activation w.r.t GAP output

$$\frac{\partial a^{c,L}}{\partial F^{k,L}} = w_c^{k,L} \quad \overset{?}{=}$$

$$\frac{\partial a^{c,L}}{\partial \mathbf{f}^{k,L}(i,j)} = w_c^{k,L} \quad ?$$



Relation between CAM and Grad-CAM

- * If the last convolutional layer is followed by a global average pooling (GAP) and softmax layer then, Grad-CAM gives

$$\alpha_k^c = \frac{1}{S} \sum_{i,j} \frac{\partial a^{c,L}}{\partial f^{k,l}(i,j)} \rightarrow \alpha_c^k = w_c^{k,L}$$

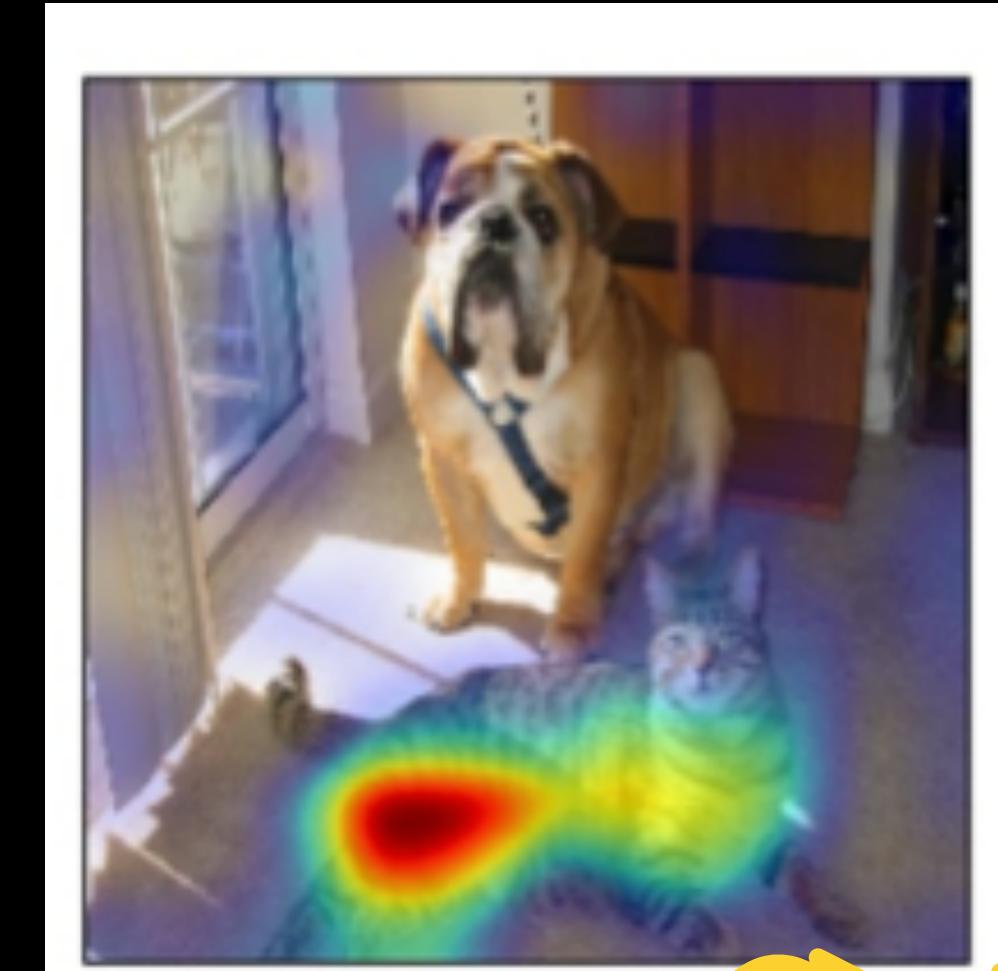
- * Grad-CAM generalizes the CAM framework to neural networks that can have convolutional networks followed by other architectures.



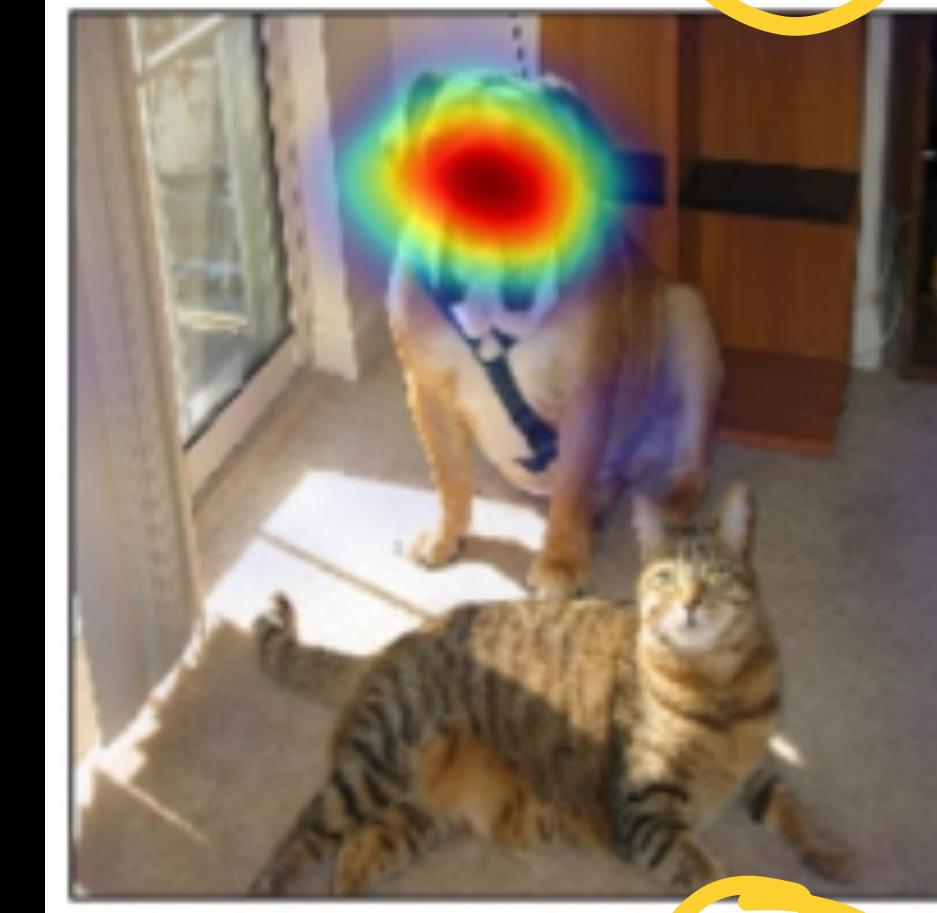
Visualizing Grad-CAM outputs



Tiger-cat



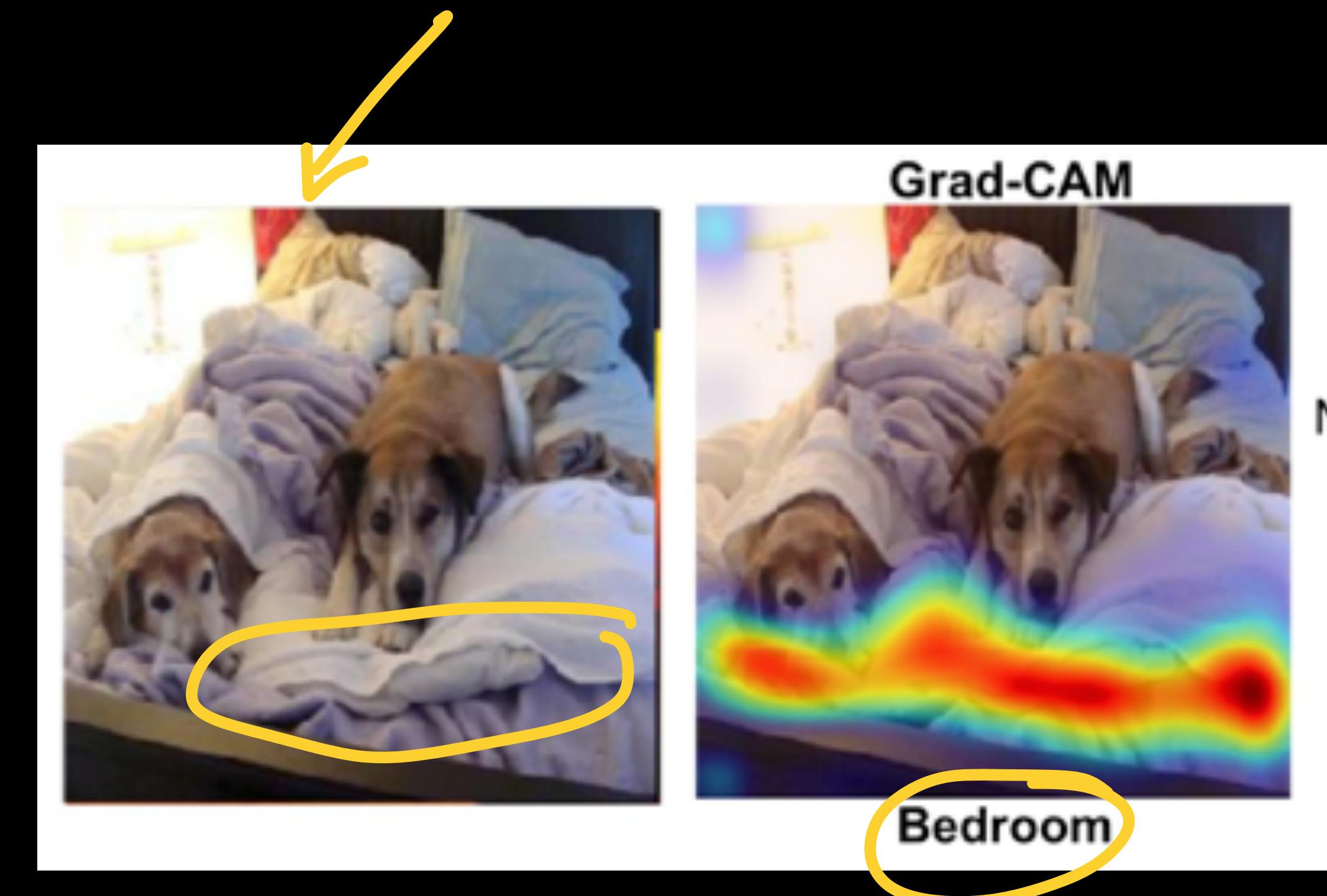
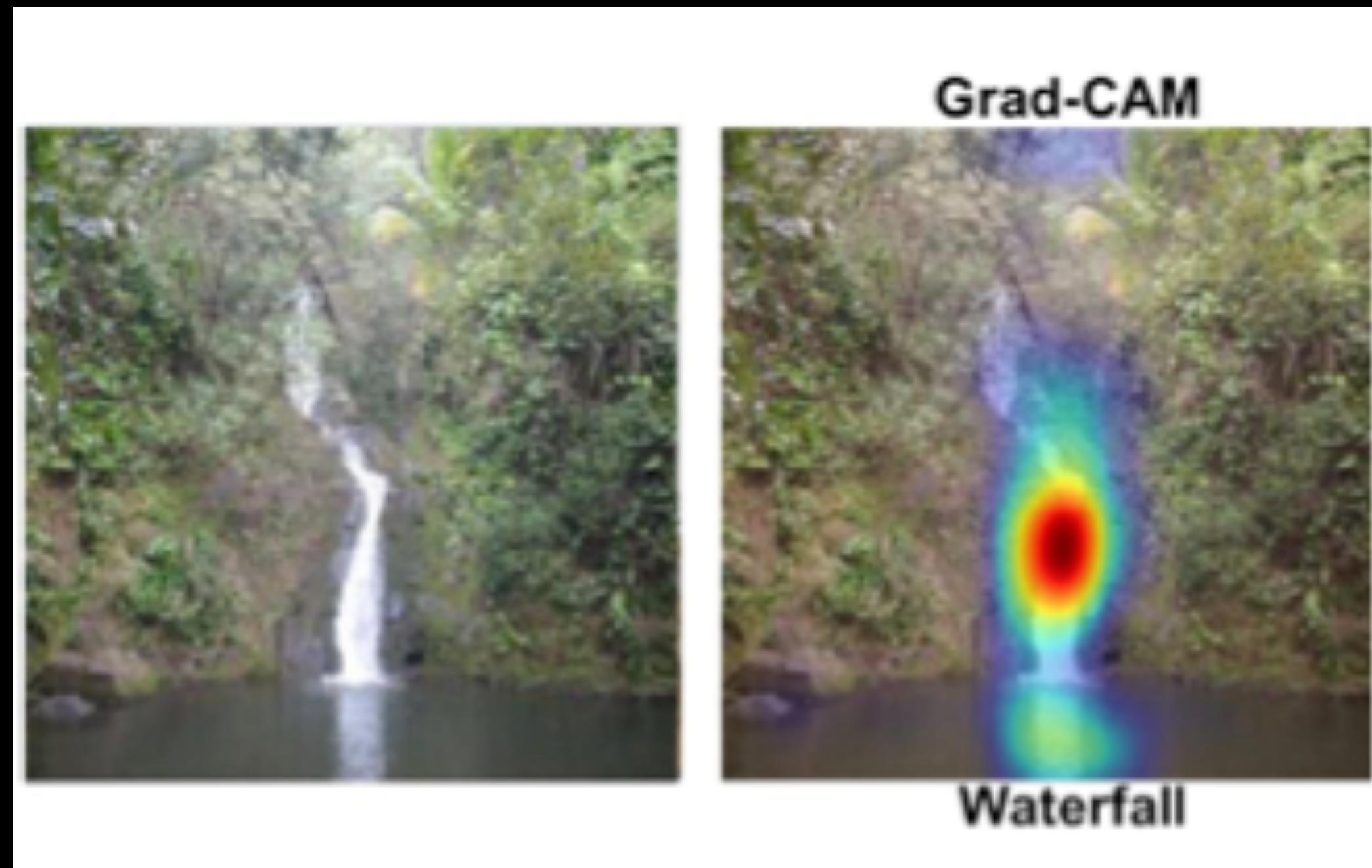
(c) Grad-CAM 'Cat'



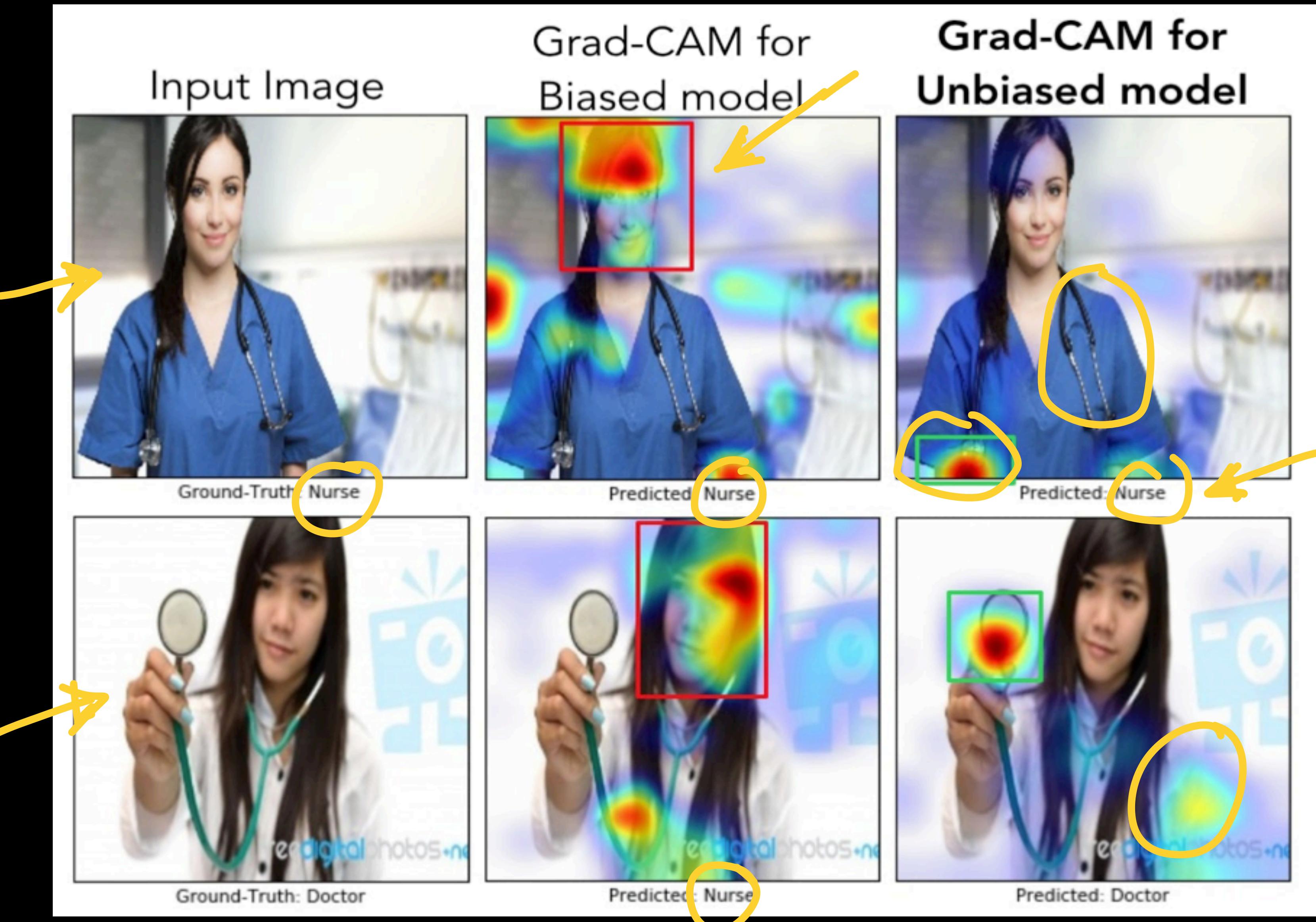
(i) Grad-CAM 'Dog'



Grad-CAM in image captioning



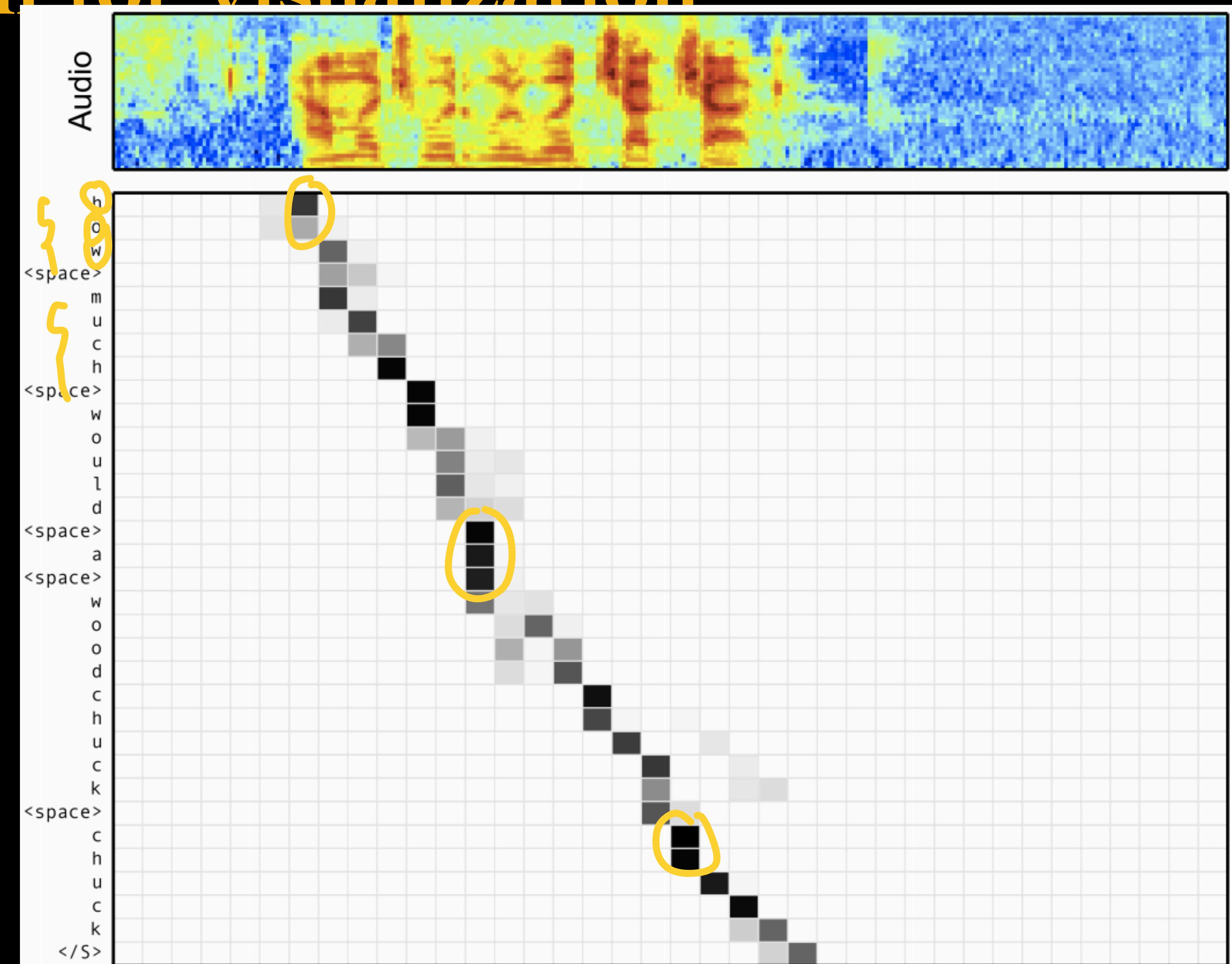
Grad-CAM for identifying model biases



Using attention for visualization



audio



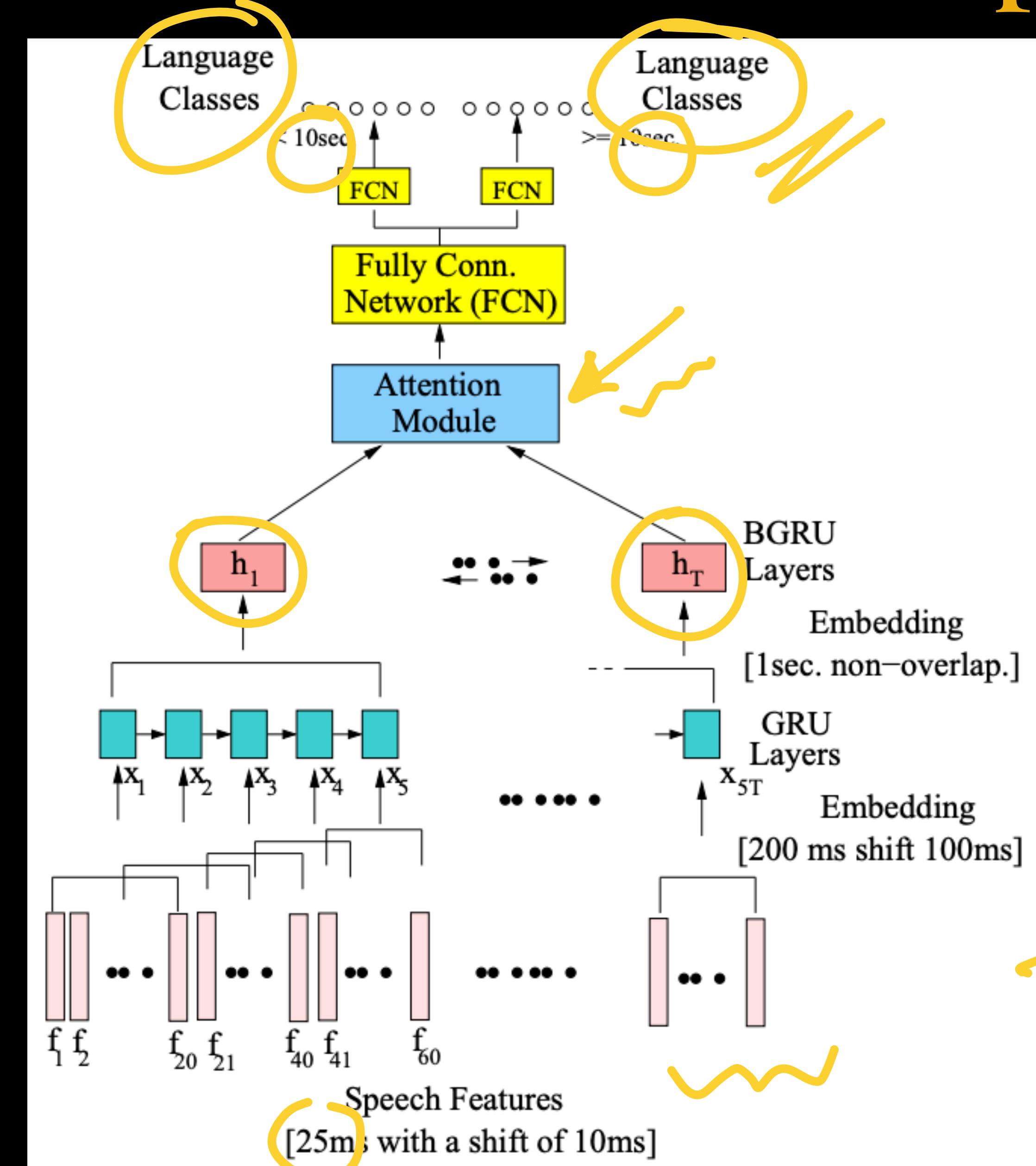
Using attention mechanism for explainability

Towards Relevance and Sequence Modeling in Language Recognition

Bharat Padi, Anand Mohan and Sriram Ganapathy, *Senior Member, IEEE*



Using attention mechanism for explainability

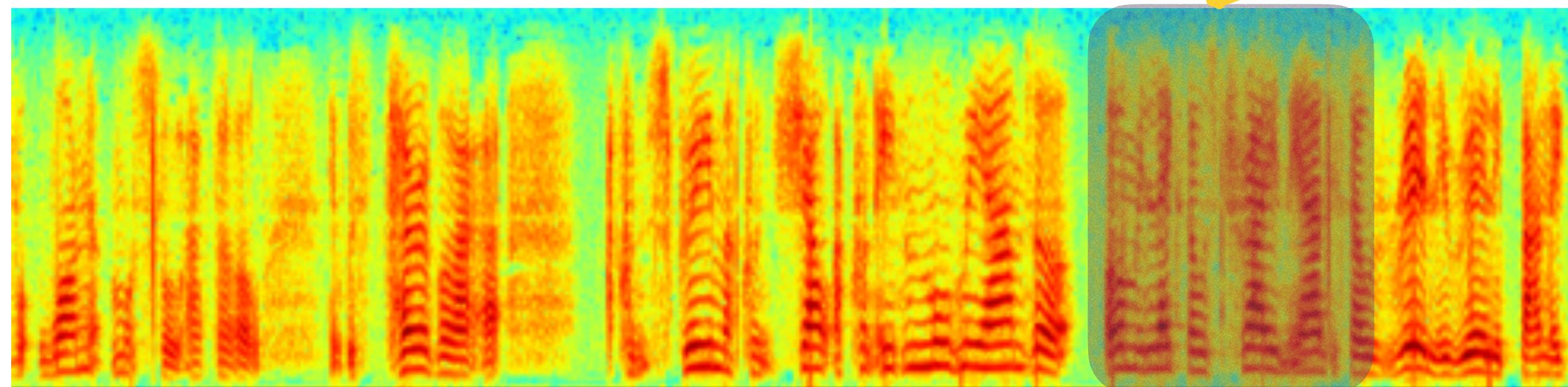


Speech Eng

A vertical black rectangle containing yellow handwritten text and symbols. At the top right is a circle with the letter 'A'. To its left is a wavy line. Below these are the numbers '15' and '40'.

Using attention mechanism for explainability

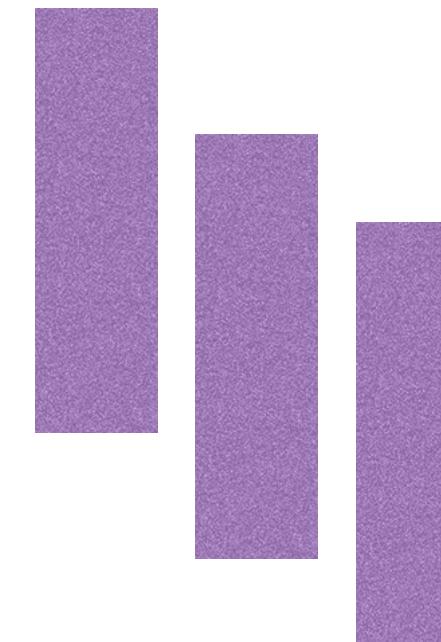
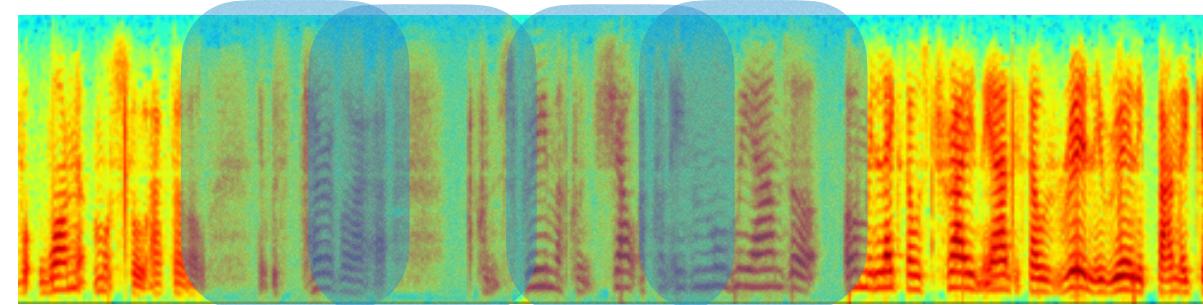
- ❑ Certain regions of the audio signal may have more information for the task than the rest.
 - ✓ May also have more signal quality than rest.
 - ✓ For example, language identification involving Eng-UK v/s Eng. US.



- ❑ Current models - use the information from audio with uniformity.

Using attention mechanism for explainability

- Derive short segment i-vectors



Sequence to label
model
using **attention**



- Attention weighs the importance of each short-term segment feature for the task.

Attention Weight

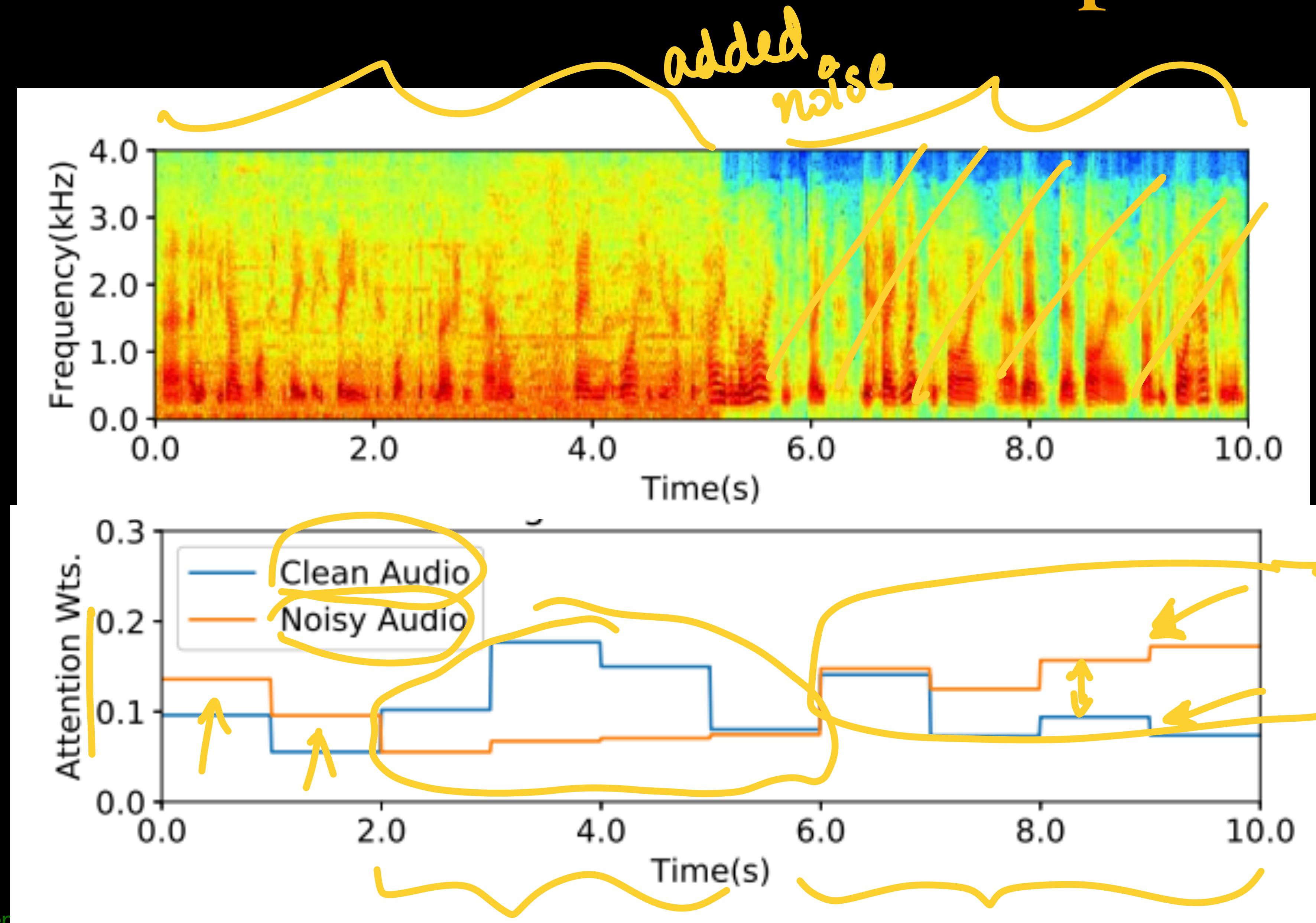
0-3s

3s-4s

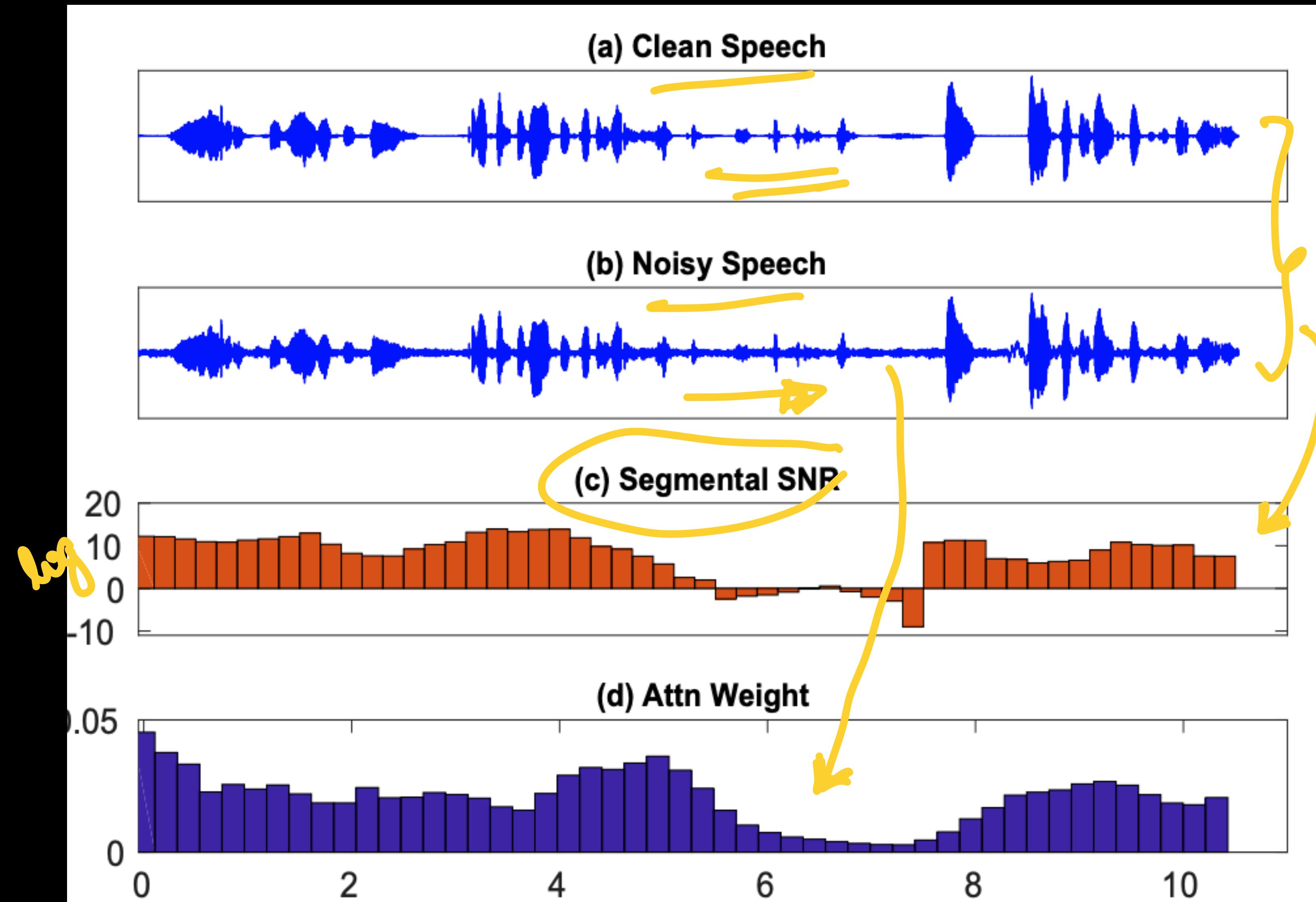
4s - 9s I couldn't scream, I couldn't shout, I couldn't even move my arms up, or my legs

9s -11s

Using attention mechanism for explainability



Using attention mechanism for visualization



Summary thus far

★ Analyzing trained neural networks

- ✓ Hierarchical representations
- ✓ Activation maps to determine saliency
- ✓ Incorporating attention mechanism for improved explainability

